

Symmetry breaking in the self-dual higher-spin theory

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(Received 8 September 2025; accepted 29 October 2025; published 18 November 2025)

We explore the symmetry-broken phase of the self-dual (chiral) sector of higher-spin theory in four dimensions. To that end, we construct a two-parameter vacuum that breaks the anti-de Sitter (AdS) symmetry but remains symmetric under the leftover Poincaré algebra in three dimensions. The vacuum nonzero fields include spin-two AdS frame fields and a scalar, which has a profile that extends along the AdS radial direction. The two free parameters correspond to two scalar branches of conformal dimensions $\Delta = 1$ and $\Delta = 2$. Focusing on the $\Delta = 1$ branch, we analyze the dynamics of free fields around this vacuum and examine its holographic dual. We observe that certain higher spin states decouple in the broken phase. This is illustrated by a set of gauge fluctuations, which acquire no source from higher-spin currents, leading to their complete decoupling, except for the gauge field associated with spin one. The dual higher-spin currents appear to be disentangled from the gauge fields and generally do not conserve; however, their lower-spin components with helicities $s = -1, 0$, and $\pm 1/2$ remain unaffected by the symmetry breaking. Notably, the helicity $s = +1$ current, while deformed, remains conserved.

DOI: [10.1103/nmxv-c8kx](https://doi.org/10.1103/nmxv-c8kx)

I. INTRODUCTION

Unitary higher-spin gauge theories (HS) in flat spacetime face significant challenges due to various no-go theorems [1–3]; see also [4,5] for a more recent account and [6] for review. However, introducing a nonzero cosmological constant Λ bypasses these flat-space restrictions and allows for higher-spin interactions, as demonstrated long ago by Fradkin and Vasiliev at the cubic level [7,8]. These interaction vertices involve negative powers of Λ , which renders the straightforward limit $\Lambda \rightarrow 0$ meaningless.¹ Cubic HS interactions have been extensively studied in the literature; see [12] for a substantial list of references and [13–16] for more recent results, but research on higher-order interactions in AdS remains limited [17–19]. Nevertheless, it has long been established that the cubic

Fradkin-Vasiliev interactions can be completed to all orders in four dimensions at the level of classical equations of motion [20]. This fundamental result introduces several important concepts:

- (1) The higher-spin algebra, in which fields take values.

In four dimensions, the HS algebra is particularly straightforward to realize via the Moyal algebra of commuting variables $Y_A = (y_\alpha, \bar{y}_{\dot{\alpha}})$, where α and $\dot{\alpha}$ are $sl(2, \mathbb{C})$ indices that take on two values. The product in this algebra is defined as follows:

$$\begin{aligned} f(y, \bar{y}) * g(y, \bar{y}) \\ = \int_{U, V} f(y + u, \bar{y} + \bar{u}) g(y + v, \bar{y} + \bar{v}) e^{iu_\alpha v^\alpha + i\bar{u}_{\dot{\alpha}} \bar{v}^{\dot{\alpha}}}, \end{aligned} \quad (1.1)$$

where the integration goes over $U = (u, \bar{u})$ and $V = (v, \bar{v})$ with the measure chosen such that $1 * 1 = 1$.

- (2) Deformation procedure: This procedure is based on the unfolded formulation [21] (for applications and quantum extension, see [22–24]). It suggests that a convenient set of fields consists of gauge connections represented as space-time 1-forms $\omega(Y|x) = dx^\mu \omega_\mu(Y|x)$ and 0-forms $C(Y|x)$. The latter can be viewed as HS curvatures for the connections ω at the linearized level. Both ω and C take values in the HS

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¹One can make sense of this limit by Λ -rescaling HS fields, but the no-go's still prevent local interactions at higher orders. Notably, the self-dual interactions terminate at the cubic order in the light-cone frame as follows from Metsaev's analysis [9,10]; see also [11].

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algebra. The deformation represents an action of the HS algebra and can be schematically expressed as

$$d_x \omega = \sum_{n=0}^{\infty} \sum_{i+j=n} \eta^i \bar{\eta}^j \mathcal{V}_{i,j}(\omega, \omega, C^n), \quad (1.2a)$$

$$d_x C = \sum_{n=1}^{\infty} \sum_{i+j=n-1} \eta^i \bar{\eta}^j \Upsilon_{i,j}(\omega, C^n), \quad (1.2b)$$

where $\mathcal{V}$ and Υ are polylinear functionals of ω and C . For example, we define $\mathcal{V}(\omega, \omega, C^2) := \mathcal{V}(\omega, \omega, C, C)$, which is linear in each argument. A constant η is an arbitrary phase parameter of the four-dimensional theory with $\bar{\eta}$ being its complex conjugate. The parameter breaks parity unless $\eta = 1$ or $\eta = i$. We refer to the functionals $\mathcal{V}$ and Υ as 1-form and 0-form vertices, respectively. Their explicit forms arise from the consistency $d_x^2 = 0$ and from the *initial data* corresponding to the nondeformed HS algebra action at the lowest order. Specifically,

$$\begin{aligned} \mathcal{V}_{0,0}(\omega, \omega) &= -\omega * \omega, \\ \Upsilon_{0,0}(\omega, C) &= -\omega * C + C * \pi(\omega), \end{aligned} \quad (1.3)$$

where $\pi f(y, \bar{y}) := f(-y, \bar{y})$ is a certain automorphism of the HS algebra that ensures the free equations following from (1.2) align with those of Fronsdal [25].

- (3) Vasiliev's generating equations: These Eq. [20] allow for a systematic reconstruction of $\mathcal{V}$ and Υ from (1.2) up to a freedom in field redefinition; for reviews, see [26–28].

Despite Vasiliev's approach providing access to any order of HS interactions, several technical and conceptual challenges remain. On the technical side, reconstructing the C^3 vertices and higher becomes increasingly complicated, see, e.g., [29,19]. More importantly, there is a natural freedom in field representatives, which means that the appropriate field variables corresponding to minimal (in terms of derivatives) interactions are not fully understood. This issue is known as the locality problem [30–33] and is currently the focus of intense research; for quite a recent work in this direction, see [34,35].

The locality of the theory in AdS beyond the cubic order remains uncertain. Arguments based on HS holography [36–38] suggest that it is not local, particularly starting from the quartic order [17,39]. These arguments indicate a wild nonlocality of the form $1/\square$, which, if accurate, would pose challenges for HS theories in AdS, similar to those observed in the Minkowski case.

On the other hand, direct calculations from the bulk [19] indicate a moderate nonlocality at the quartic order, which might be in tension with holographic expectations. However, let us emphasize that the holographic locality

argument heavily depends on the assumption that the HS algebra remains undeformed at the boundary in interactions. Whether this assumption holds true is an open question.

A. Holomorphic sector

The locality problem becomes significantly simpler in the closed sector of the theory, which can be singled out by setting $\eta = 0$ ($\bar{\eta} = 0$), corresponding to the (anti)self-dual HS theory [20]. This sector is called (anti)holomorphic, also known as (anti)chiral. In the system (1.2), the relevant vertices are $\mathcal{V}_{0,n}$ and $\Upsilon_{0,n}$, or alternatively, $\mathcal{V}_{n,0}$ and $\Upsilon_{n,0}$. We refer to these as (anti)holomorphic vertices. It is worth emphasizing that relaxing the complex-conjugation $\bar{\eta} = \eta^*$ is not compatible with the reality conditions for HS fields (these can be found in, e.g., [26]). Therefore, the holomorphic sector is essentially complex.

In the self-dual case $\eta = 0$, Eq. (1.2) simplify to the form

$$d_x \omega = \sum_{n=0}^{\infty} \mathcal{V}_n(\omega, \omega, C^n), \quad (1.4a)$$

$$d_x C = \sum_{n=1}^{\infty} \Upsilon_n(\omega, C^n), \quad (1.4b)$$

where we set $\bar{\eta} = 1$ for convenience and use the simplified notation $\mathcal{V}_n := \mathcal{V}_{0,n}$, $\Upsilon_n := \Upsilon_{0,n}$. At the free level on AdS, the holomorphic sector also differs from the linearized full theory in that only HS Weyl tensors of helicities $s \leq -1$ source the HS gauge fields.² In contrast, the full theory allows both helicities $s \geq 1$ and $s \leq -1$ to source these fields. For other recent advances in chiral HS theory, see [40–46] and also a notable 6D extension considered in [47].

It has been conjectured in [48] that the holomorphic vertices are local to all orders. This conjecture was tested up to the C^3 order [49] as new necessary tools were developed in a series of papers [48,50–53]. The all-order locality was confirmed in [54], where a Vasiliev-like generating system that reproduces Eq. (1.4) was proposed. The structure of this system makes the holomorphic locality manifest in natural variables. Furthermore, the vertices can be explicitly extracted to all orders [55] (see also [56], where local vertices were identified from the divergent homological perturbations). They exhibit what is known as projectively compact spin locality [57], which leads to space-time locality with a minimal number of derivatives.

B. Higher-spin symmetry breaking

The longstanding idea, originating from earlier works [58–60], proposes the existence of a tensionless limit in superstring theory, which is believed to reveal a huge

²This may not be true on other backgrounds, such as the one we will consider in this paper.

symmetry associated with massless gauge fields. In this context, the unbroken phase of superstring theory is viewed as a foundational hypothetical HS theory, while the superstring emerges from its symmetry-broken phase. These concepts have been further explored in the literature [61–65], but progress has been limited due to problematic interpretation in the flat superstring background, and the fact that string theory in AdS space has yet to be developed. For an interesting proposal of a HS theory that allegedly has room for stringy states, see [66] and its subsequent development [67].

Another intriguing suggestion from [68] is that string theory might emerge at the boundary of AdS space in the HS broken phase.³ In our paper, we aim to follow this line of reasoning, albeit in a simplified context that allows for a more detailed analysis. To align with Metsaev’s framework from [68], it is essential to establish a clear mechanism for how the global symmetry of AdS space in HS theory breaks down to the symmetry of the Minkowski boundary in one lower dimension, which could correspond to a stringy vacuum. However, addressing this issue within the complete HS theory is challenging due to the problem of nonlocality. Therefore, we limit ourselves to a small sector. Specifically, we focus on the holomorphic HS sector, which is important because it is closed and yet describes local interactions in spacetime at all orders of perturbation theory. This makes it a valuable toy model for studying symmetry breaking.

Our approach begins with the search for a holomorphic vacuum that mildly breaks AdS symmetry while preserving the Poincaré symmetry of its 3D boundary. The existence of such a vacuum has already been explored for the off-shell d -dimensional bosonic equations in [73], with a solution provided in [74]; see also [75]. We revisit this problem within the purely holomorphic sector and demonstrate that the required vacuum, which satisfies Eq. (1.4), does indeed exist and has a schematic form

$$\omega_0 = \Omega_{\text{AdS}}, \quad (1.5)$$

$$C_0 \rightarrow \phi = \nu_1 z + \nu_2 z^2. \quad (1.6)$$

The vacuum contains the standard AdS connection (1.5). However, the global AdS symmetry is broken due to the presence of a nonzero matter expectation (1.6), which is zero in the standard HS vacuum. In our case, the vacuum value includes only a specific scalar mode ϕ that depends on the inverse AdS radial distance z , associated with the Poncaré metric [see Eq. (3.3)]. The two coefficients, ν_1 and ν_2 , can be arbitrary.

³In the lower-dimensional topological case, a related analysis has been conducted in [69]. The earlier analysis of the tensionless strings on orbifolds is available in [70–72].

Next, we further restrict ourselves to the case where $\nu_2 = 0$, allowing ν_1 to remain arbitrary. We then study the linearized fluctuations around the vacuum (1.5), (1.6)

$$\omega = \omega_0 + \mathbf{w} + \dots, \quad C = C_0 + \mathcal{C} + \dots \quad (1.7)$$

In the unbroken case with $C_0 = 0$, these fluctuations correspond to free massless fields of helicities $s \leq -1$ propagating on the AdS background. The boundary dual of these fluctuations leads to a set of conserved 3D currents. These currents typically source the boundary HS connections and take a remarkable form of a tensor product of two singletons. This fundamental result of Flato and Fronsdal [76] lays the groundwork for HS holography in [77]; see also [78,79]. We revisit the dual analysis in the HS broken case with $C_0 \neq 0$, where all types of helicities are present and arrive at the following results:

- (i) A set of HS currents with helicities $s \geq -1$ appears to disentangle from HS connections, forming a closed 0-form module. The currents generally do not conserve, with the exception of the helicity $s = \pm 1$ current.
- (ii) Naturally, the current equations are deformed by the symmetry-breaking parameter $\nu = \nu_1$, but this is not the case for helicities $s = -1, 0$ and $s = \pm \frac{1}{2}$, where they remain the same as in the unbroken case.
- (iii) We observe a set of HS connections that completely decouple from the system, having no currents as sources. The only exception is a spin one connection, which is sourced by the corresponding Maxwell current.

Brief summary Our toy model study of the HS breaking mechanism in the self-dual sector of HS theory involves a few key steps. First, we identify an exact solution that breaks the global HS symmetry associated with AdS space, reducing it to the symmetry of 3D Minkowski spacetime. This solution, which we refer to as the symmetry-broken vacuum, includes two parameters: ν_1 and ν_2 related to two branches of the vacuum scalar expectations. For our analysis, we focus on the case where $\nu_2 = 0$.

Next, we examine the dynamics of free fields around this new vacuum by deriving the corresponding linear equations for a specific set of fluctuations. We make an intriguing observation: the resulting linear system can be reformulated in terms of 3D off-shell currents. This situation is reminiscent of the Flato and Fronsdal theorem, which relates free gauge fields in AdS space to conserved boundary currents. However, in our case of broken symmetry, these currents generally do not conserve, leading us to identify a structure of nonconservation.

Our findings highlight an intriguing aspect of the HS symmetry breaking mechanism. We demonstrate, loosely speaking, that higher spin currents are more likely to be broken compared to their lower spin counterparts. The breaking degree increases with the spin: the higher the spin,

the more contributions it receives from smaller spins. In particular, a spin-one current appears to be conserved, despite the fact that its equation is deformed by the symmetry-breaking parameter ν .

This paper is structured as follows. Section II introduces the generating equations for HS self-dual interactions and presents the corresponding interaction vertices. Section III proposes a vacuum state with broken HS symmetry. Section IV discusses the dynamics of free fields around this vacuum, while in Sec. V we examine its holographic dual. Finally, we conclude in Sec. VI. Additionally, the paper includes five technical appendices for further reference.

II. EQUATIONS OF MOTION

The unfolded form of the HS equations (1.2) arises order by order as a solution to the Vasiliev system [20]. In the self-dual case, where $\bar{\eta} = 0$, it is convenient to use the generating equations proposed in [54].⁴ In particular, locality of HS interactions in the self-dual case is established in [54] to all orders, and the corresponding vertices are available.

To formulate the equations, we introduce an auxiliary spinor variable⁵ $z_\alpha = (z_1, z_2)$. This variable expands the original Y -space and allows us to introduce the field $W(z; y, \bar{y})$, which is designed to capture nonlinear corrections in ω and C through its dependence on z

$$W := \omega(y, \bar{y}) + W_1[\omega, C](z; y, \bar{y}) + W_2[\omega, C, C](z; y, \bar{y}) + \dots \quad (2.1)$$

Notice that while C can enter W nonlinearly, the field ω being a 1-form enters W strictly linearly. The equations that generate self-dual HS interactions take the following form [54]:

$$d_x W + W * W = 0, \quad (2.2a)$$

$$d_z W + \{W, \Lambda\}_* + d_x \Lambda = 0, \quad (2.2b)$$

$$d_x C + (W(z'; y, \bar{y}) * C - C * W(z'; -y, \bar{y}))|_{z'=-y} = 0. \quad (2.2c)$$

They contain two types of differentials: the space-time $d_x = dx^\alpha \frac{\partial}{\partial x^\alpha}$, and the auxiliary one $d_z = dz^\alpha \frac{\partial}{\partial z^\alpha}$. There is the auxiliary connection Λ associated with the d_z -direction

⁴We expect that equations from [54] should follow in a star-product reordering limit from those of Vasiliev but, strictly speaking, the equivalence of the two systems was established only for a few orders (see [55]). While it may seem unlikely, the possibility that they could diverge at sufficiently high orders was not ruled out.

⁵The auxiliary spinor z should not be confused with the Poincaré radial coordinate z .

$$\Lambda[C] = dz^\alpha z_\alpha \int_0^1 d\tau \tau C(-\tau z, \bar{y}) e^{i\tau zy}, \quad (2.3)$$

which satisfies

$$d_z \Lambda = C * \gamma, \quad \gamma = \frac{1}{2} dz_\beta dz^\beta \exp izy. \quad (2.4)$$

For brevity throughout the text, we frequently use the condensed notation for spinor contractions

$$\xi \eta := \xi_\alpha \eta^\alpha = -\eta \xi. \quad (2.5)$$

The large star product is

$$(f * g)(z, y; \bar{y}) = \int f(z + u', y + u; \bar{y}) \star g(z - v, y + v + v'; \bar{y}) \times \exp(iu_\alpha v^\alpha + iu'_\alpha v'^\alpha), \quad (2.6)$$

where the measure in the integration over u, u', v, v' is such that $1 * 1 = 1$, while $\star$ is the Moyal product with respect to the variables $\bar{y}$

$$f(\bar{y}) \star g(\bar{y}) = \int f(\bar{y} + \bar{u}) g(\bar{y} + \bar{v}) e^{i\bar{u} \bar{v}}. \quad (2.7)$$

The following action can be easily derived from (2.6) and (2.7):

$$y_\alpha * = y_\alpha + i \frac{\partial}{\partial y^\alpha} - i \frac{\partial}{\partial z^\alpha}, \quad z_\alpha * = z_\alpha + i \frac{\partial}{\partial y^\alpha}, \quad (2.8a)$$

$$*y_\alpha = y_\alpha - i \frac{\partial}{\partial y^\alpha} - i \frac{\partial}{\partial z^\alpha}, \quad *z_\alpha = z_\alpha + i \frac{\partial}{\partial y^\alpha}, \quad (2.8b)$$

$$\bar{y}_{\dot{\alpha}} * = \bar{y}_{\dot{\alpha}} + i \frac{\partial}{\partial \bar{y}^{\dot{\alpha}}}, \quad *\bar{y}_{\dot{\alpha}} = \bar{y}_{\dot{\alpha}} - i \frac{\partial}{\partial \bar{y}^{\dot{\alpha}}}. \quad (2.8c)$$

In particular,

$$[y_\alpha, y_\beta]_* = 2i\epsilon_{\alpha\beta}, \quad [\bar{y}_{\dot{\alpha}}, \bar{y}_{\dot{\beta}}]_* = 2i\epsilon_{\dot{\alpha}\dot{\beta}}, \quad (2.9)$$

$$[y_\alpha, z_\beta]_* = [\bar{y}_{\dot{\alpha}}, z_\beta]_* = [z_\alpha, z_\beta]_* = 0.$$

For z -independent functions the star product (2.6) is just the Moyal product (1.1).

Let us clarify the role of each equation from (2.2) in relation to the unfolded Eq. (1.4) they generate.

- (i) Equation (2.2a): When we substitute (2.1) into this equation, we arrive at (1.4a).
- (ii) Equation (2.2b): This equation specifies the necessary corrections in (2.1) and ensures that the z -dependence is eliminated from (2.2a). It can be solved order by order in C in perturbation. This procedure features ambiguity in homogeneous solution at each order, manifesting field redefinition freedom

$$W_n[\omega, C \dots C](z; Y) \rightarrow W_n[\omega, C \dots C](z; Y) + F_n[\omega, C \dots C](Y), \quad (2.10)$$

where n denotes the order of perturbations in C . A convenient way to fix this freedom is by picking the physical field $\omega(Y)$ at the zeroth order. This implies that

$$W_n(0; y, \bar{y}) = 0, \quad n \geq 1. \quad (2.11)$$

The field frame specified in (2.11) is called *canonical*.

- (iii) Equation (2.2c): Upon substituting W [which solves (2.2b)], this equation reproduces (1.4b).
- (iv) Dynamical content is collected in the 1-form $\omega(y, \bar{y})$ and the 0-form $C(y, \bar{y})$ as follows: self-dual spin S primaries are singled out by

$$\left(y^\alpha \frac{\partial}{\partial y^\alpha} + \bar{y}^{\dot{\alpha}} \frac{\partial}{\partial \bar{y}^{\dot{\alpha}}} \right) \omega = 2(S-1)\omega, \quad (2.12a)$$

$$\left(y^\alpha \frac{\partial}{\partial y^\alpha} - \bar{y}^{\dot{\alpha}} \frac{\partial}{\partial \bar{y}^{\dot{\alpha}}} \right) C = 2sC, \quad (2.12b)$$

where $s = \pm S$ denotes helicity. Those components of ω and C that do not satisfy (2.12) are expressed via derivatives of primaries on-shell.

It is important to emphasize that z' in (2.2c) is not a variable associated with the star product; rather, it is a parameter that replaces z . After completing the star product integration with respect to Y in (2.2c), we set $z' = -y$. Finally, we should stress that Eq. (2.2c) is not independent; it arises as an integrability condition, specifically the consequence of $d_z^2 = 0$ from (2.2b). Consistency of (2.2) is not trivial. It is based on the so-called projective identity [54]. A direct check of consistency, if somewhat involved, is also available; see [80].

Vertices The system (2.2) generates vertices on the right-hand sides of (1.4). The explicit form of these vertices, which corresponds to the minimal space-time local interaction, was previously determined in [55]. Below, we present the final result. The 1-form sector vertices read

$$\begin{aligned} \mathcal{V}(\omega, \omega, C^n) = & \sum_{0 \leq k_1 \leq k_2 \leq n} (-)^{k_2 - k_1 + 1} \int_{\mathcal{D}_{n+1}^{[k_1, k_2]}} d\xi d\eta \int \frac{d^2 u d^2 u' d^2 v d^2 v'}{(2\pi)^4} e^{iuv + iu'v'} \left(\prod_{j=1}^{k_1} \star C(\xi_j v + \eta_j v', \bar{y}) \right) \\ & \star (\partial_\alpha)^n \omega \left(\xi_{n+1} y + u - \frac{S_n^{[k_1, k_2]}}{2} v', \bar{y} \right) \star \left(\prod_{j=k_1+1}^{k_2} \star C(\xi_j v + \eta_j v', \bar{y}) \right) \\ & \star (\partial^\alpha)^n \omega \left(\eta_{n+1} y + u' + \frac{S_n^{[k_1, k_2]}}{2} v, \bar{y} \right) \star \left(\prod_{l=k_2+1}^n \star C(\xi_l v + \eta_l v', \bar{y}) \right), \end{aligned} \quad (2.13)$$

where $\partial_\alpha \omega(a, \bar{a}) := \frac{\partial}{\partial a^\alpha} \omega(a, \bar{a})$,

$$S_n^{[k_1, k_2]} = 1 - \sum_{s=1}^{k_2} \xi_s + \sum_{s=k_2+1}^n \xi_s + \sum_{s=1}^{k_1} \eta_s - \sum_{s=k_1+1}^n \eta_s + \sum_{i < j}^n (\xi_i \eta_j - \xi_j \eta_i), \quad (2.14)$$

and the compact (ξ, η) -integration domain is

$$\mathcal{D}_{n+1}^{[k_1, k_2]} = \begin{cases} \eta_1 + \dots + \eta_{n+1} = 1, & \eta_i \geq 0, \\ \xi_1 + \dots + \xi_{n+1} = 1, & \xi_i \geq 0, \\ \eta_i \xi_{i+1} - \eta_{i+1} \xi_i \geq 0, & i \in [0, k_1 - 1], \\ \eta_i \xi_{i+1} - \eta_{i+1} \xi_i \leq 0, & i \in [k_1 + 1, k_2 - 1], \\ \eta_i \xi_{i+1} - \eta_{i+1} \xi_i \geq 0, & i \in [k_2 + 1, n], \end{cases} \quad (2.15)$$

where η_0 and ξ_0 should be identified with η_{n+1} and ξ_{n+1} correspondingly.

The vertices from the 0-form sector (1.4b) are

$$\begin{aligned} \Upsilon(\omega, C^n) = & (-i)^{n-1} \sum_{k=0}^n (-)^{k+1} \int_{\mathcal{D}_n^{[k]}} d\xi d\eta \int \frac{d^2 u d^2 v}{(2\pi)^2} e^{iuv} \\ & \times \left(\prod_{j=1}^k \star C(\xi_j y + \eta_j v, \bar{y}) \right) \star (y^\alpha \partial_\alpha)^{n-1} \omega(S_n^{[k]} y + u, \bar{y}) \star \left(\prod_{j=k+1}^n \star C(\xi_j y + \eta_j v, \bar{y}) \right) \end{aligned} \quad (2.16)$$

with

$$\mathcal{D}_n^{[k]} = \begin{cases} \eta_1 + \dots + \eta_n = 1, & \eta_i \geq 0, \\ \xi_1 + \dots + \xi_n = 1, & \xi_i \geq 0, \\ \eta_i \xi_{i+1} - \eta_{i+1} \xi_i \leq 0, & i \in [1, k-1], \\ \eta_i \xi_{i+1} - \eta_{i+1} \xi_i \geq 0, & i \in [k+1, n-1], \end{cases} \quad (2.17)$$

and

$$S_n^{[k]} = -\sum_{s=1}^k \xi_s + \sum_{s=k+1}^n \xi_s + \sum_{i<j}^n (\xi_i \eta_j - \xi_j \eta_i). \quad (2.18)$$

The integration domains (2.17) enjoy the following important property:

$$\bigsqcup_{k\text{-odd}} \mathcal{D}_n^{[k]} = \bigsqcup_{k\text{-even}} \mathcal{D}_n^{[k]}, \quad (2.19)$$

which appears very helpful in practice. The symbol $\bigsqcup$ is understood as union up to a set of measure zero. Note that domains intersect only along the sets of measure zero, which can be omitted for integration domains. Since Eq. (2.19) was not previously observed in [55], we prove it in Appendix B.

III. VACUUM SOLUTION

HS theories admit a natural vacuum, which is the AdS space-time. This is also the case with the self-dual sector. Specifically, Eqs. (2.2) are satisfied for

$$C_0 = 0, \quad (3.1a)$$

$$W_0 := \Omega(y, \bar{y}) = -\frac{i}{4} (\omega_{\alpha\beta} y^\alpha y^\beta + \bar{\omega}_{\dot{\alpha}\dot{\beta}} \bar{y}^{\dot{\alpha}} \bar{y}^{\dot{\beta}} + 2\mathbf{e}_{\alpha\dot{\beta}} y^\alpha \bar{y}^{\dot{\beta}}), \quad (3.1b)$$

where 1-forms ω and $\mathbf{e}$ are associated respectively with the Lorentz connection and vierbein of the four-dimensional AdS. The corresponding Cartan equations following from (2.2) read⁶

$$d_x \omega_{\alpha\beta} + \omega_{\alpha\gamma} \wedge \omega^\gamma_\beta + \mathbf{e}_{\alpha\dot{\gamma}} \wedge \mathbf{e}_{\beta}^{\dot{\gamma}} = 0, \quad (3.2a)$$

$$d_x \bar{\omega}_{\dot{\alpha}\dot{\beta}} + \bar{\omega}_{\dot{\alpha}\dot{\gamma}} \wedge \bar{\omega}^{\dot{\gamma}}_{\dot{\beta}} + \mathbf{e}_{\gamma\dot{\alpha}} \wedge \mathbf{e}^{\gamma}_{\dot{\beta}} = 0, \quad (3.2b)$$

$$d_x \mathbf{e}_{\alpha\dot{\alpha}} + \omega_{\alpha\gamma} \wedge \mathbf{e}^{\gamma}_{\dot{\alpha}} + \bar{\omega}_{\dot{\alpha}\dot{\gamma}} \wedge \mathbf{e}_{\alpha}^{\dot{\gamma}} = 0. \quad (3.2c)$$

A convenient choice of the AdS coordinates in what follows is the Poincaré ones

$$ds^2 = \frac{1}{z^2} (dz^2 + dx_{\alpha\beta} dx^{\alpha\beta}), \quad (3.3)$$

where we introduced the boundary three-dimensional coordinates⁷

$$x_{\alpha\beta} = x_{\beta\alpha}, \quad (3.4)$$

and the radial coordinate z . The background connections (3.2) can be chosen to be

$$\omega_{\alpha\beta} = \frac{i}{2z} dx_{\alpha\beta}, \quad (3.5a)$$

$$\bar{\omega}_{\dot{\alpha}\dot{\beta}} = -\frac{i}{2z} dx_{\dot{\alpha}\dot{\beta}}, \quad (3.5b)$$

$$\mathbf{e}_{\alpha\dot{\beta}} = \frac{i\epsilon_{\alpha\dot{\beta}} dz - dx_{\alpha\dot{\beta}}}{2z}, \quad (3.5c)$$

where the $3+1$ splitting is achieved by introducing

$$\begin{aligned} \epsilon_{\alpha\dot{\beta}} &= -\epsilon_{\dot{\beta}\alpha}, & \epsilon^{\alpha\dot{\beta}} &= -\epsilon^{\dot{\beta}\alpha}, \\ \epsilon_{\alpha\dot{\beta}} \epsilon^{\beta\dot{\beta}} &= \delta_\alpha^\beta, & \epsilon_{\alpha\dot{\alpha}} \epsilon^{\alpha\dot{\beta}} &= \delta_{\dot{\alpha}}^{\dot{\beta}} \end{aligned} \quad (3.6)$$

corresponding to a unit vector $v_{\alpha\dot{\beta}} = i\epsilon_{\alpha\dot{\beta}}$ along the z direction.⁸ We use the mixed epsilon to convert dotted and undotted indices according to the following convention:

$$\bar{y}_\alpha := \bar{y}^{\dot{\beta}} \epsilon_{\dot{\beta}\alpha}, \quad y_{\dot{\alpha}} := y^\beta \epsilon_{\beta\dot{\alpha}}. \quad (3.7)$$

$$x_{\alpha\dot{\beta}} := x_\alpha^\beta \epsilon_{\beta\dot{\beta}}, \quad x_{\dot{\alpha}\beta} = x^{\alpha\dot{\beta}} \epsilon_{\alpha\dot{\alpha}} \epsilon_{\beta\dot{\beta}}. \quad (3.8)$$

Note that both $x_{\alpha\dot{\beta}}$ and $x_{\dot{\alpha}\beta}$ are not independent; rather, they are expressed via $x_{\alpha\beta}$. In these terms, the Poincaré vacuum connection amounts to

$$\Omega = \frac{1}{8z} dx^{\alpha\beta} (y + i\bar{y})_{\alpha\dot{\beta}}^2 + \frac{dz}{4z} y\bar{y}. \quad (3.9)$$

Introducing

$$y_\alpha^\pm := y_\alpha \pm i\bar{y}_\alpha, \quad [y_\alpha^\pm, y_\beta^\pm]_* = 0, \quad (3.10)$$

we have various bilinears of $y^\pm$ to form the 3D conformal algebra $o(2,2)$. Specifically,

$$P_{\alpha\beta} = iy_\alpha^+ y_\beta^+, \quad (3.11a)$$

$$L_{\alpha\beta} = i(y_\alpha^+ y_\beta^- + y_\beta^+ y_\alpha^-), \quad (3.11b)$$

$$K_{\alpha\beta} = iy_\alpha^- y_\beta^-, \quad (3.11c)$$

⁶We set the cosmological constant $\Lambda = -1$ for our convenience.

⁷To avoid confusion, we use x to represent four-dimensional coordinates, while the three-dimensional slice is represented by x .
⁸The factor of i is due to the reality conditions $v^\dagger = v$.

$$D = \frac{i}{8} y_{\bar{\alpha}} \bar{y}^{+\alpha} = -\frac{1}{4} y \bar{y}, \quad (3.11d)$$

where P , L , K , and D are the generators of translations, Lorentz boosts, special conformal transformations, and dilatation, respectively. The commutation relations read

$$[P_{\alpha\beta}, L_{\mu\nu}] = -4(\epsilon_{\alpha\nu} P_{\mu\beta} + \epsilon_{\beta\nu} P_{\mu\alpha} + \epsilon_{\alpha\mu} P_{\nu\beta} + \epsilon_{\beta\mu} P_{\nu\alpha}), \quad (3.12a)$$

$$[L_{\alpha\beta}, L_{\mu\nu}] = 4(\epsilon_{\alpha\mu} L_{\beta\nu} + \epsilon_{\beta\mu} L_{\alpha\nu} + \epsilon_{\alpha\nu} L_{\beta\mu} + \epsilon_{\beta\nu} L_{\alpha\mu}), \quad (3.12b)$$

$$[K_{\alpha\beta}, P_{\mu\nu}] = -2(\epsilon_{\alpha\mu} L_{\beta\nu} + \epsilon_{\alpha\nu} L_{\beta\mu} + \epsilon_{\beta\mu} L_{\alpha\nu} + \epsilon_{\beta\nu} L_{\alpha\mu}) - 32(\epsilon_{\alpha\mu} \epsilon_{\beta\nu} + \epsilon_{\alpha\nu} \epsilon_{\beta\mu}) D, \quad (3.12c)$$

$$[D, P_{\alpha\beta}] = -P_{\alpha\beta}, \quad [D, K_{\alpha\beta}] = K_{\alpha\beta}, \quad (3.12d)$$

$$[D, L] = [P, P] = [D, D] = [K, K] = 0. \quad (3.12e)$$

A. Scalar vacuum

Interestingly, the self-dual HS theory admits another simple vacuum, where the background space is still AdS given by (3.9), while all fields vanish except for the scalar that spreads along the direction z

$$\phi = \nu_1 z + \nu_2 z^2, \quad (3.13)$$

where ν_1 and ν_2 are arbitrary constants. Notice that the scalar satisfies the free equation of motion in AdS and represents an arbitrary mixture of its two conformal branches of conformal dimensions $\Delta = 1$ and $\Delta = 2$. As a solution of the generating Eq. (2.2), it has the following form:

$$W_0 = \Omega + \nu_2 \cdot \frac{iz}{2} dx^{\alpha\beta} z_{\alpha} z_{\beta} \int_0^1 d\tau \tau (1 - \tau) e^{i\tau z y^+}, \quad (3.14)$$

$$C_0 = \nu_1 z \exp y \bar{y} + \nu_2 z^2 (1 + y \bar{y}) \exp y \bar{y}, \quad (3.15)$$

where y^+ is defined in (3.10) and Ω is given by (3.9). Notice that even though (3.14) departs from (3.9) when $\nu_2 \neq 0$, it still describes the AdS background in the Poincaré frame since $W|_{z=0} = \Omega$. Another way of seeing this is by substituting (3.14) into (2.2a). The scalar (3.13) arises as a nonzero vacuum expectation of the Weyl module $C_0(y, \bar{y})$ primary

$$\phi(x) := C_0(0, 0|x), \quad (3.16)$$

while the rest of the components in C are its on-shell derivatives. The dilatation operator (3.11d) acts on (3.15) in

the twisted-adjoint representation, and for each branch, one finds

$$\{D, C_0^{\Delta}\}_* = \Delta C_0^{\Delta}, \quad (3.17)$$

where

$$C_0^{\Delta=1} = \nu_1 z \exp y \bar{y}, \quad C_0^{\Delta=2} = \nu_2 z^2 (1 + y \bar{y}) \exp y \bar{y}. \quad (3.18)$$

Notably, the two branches are related to each other under the following Poincaré algebra action

$$\nu_2 [L_{\alpha\beta}, \Lambda[C_0^{\Delta=1}]]_* = \frac{2\nu_1}{z} [P_{\alpha\beta}, \Lambda[C_0^{\Delta=2}]]_*, \quad (3.19)$$

where $\Lambda[C]$ was defined in (2.3). We leave the derivation of vacuum (3.14), (3.15) to Appendix A. In what follows, we set

$$\nu_2 = 0 \quad \text{and} \quad \nu_1 := \nu, \quad (3.20)$$

postponing the general case for future investigation.

Global symmetries The new vacuum breaks the global HS symmetry to a subalgebra that includes the three-dimensional Poincaré space-time algebra, acting on the variables $x_{\alpha\beta}$ for arbitrary values of ν_1 and ν_2 (see also [74]). Although it may appear that Eqs. (3.14) and (3.15) smoothly deform the standard HS vacuum described in (3.1), resulting in a deformation of the global HS symmetry, this is not the case. Instead, the symmetry is actually broken down. This happens because (3.15) contains the following structure:

$$\mathcal{P} = 4e^{y\bar{y}}, \quad (3.21)$$

which is, on the one hand, an analytic function of y and $\bar{y}$, but on the other hand, acts as a projector in the star-product algebra

$$\mathcal{P} * \mathcal{P} = \mathcal{P} \quad (3.22)$$

that can be checked using (2.6). As a result, $\mathcal{P}$ projects away some states, acting as a Fock vacuum. Specifically,

$$y^+ * \mathcal{P} = \mathcal{P} * y^- = 0. \quad (3.23)$$

This implies that, for the fluctuations around the vacuum, the components carried by the gauge field $\omega(y^-, y^+)$, which enter the HS equations of motion through the vertex Υ from (1.3) at the lowest order, project onto states that depend either on y^+ or y^- . To see this projection in the equations explicitly, one can compute the following products for a gauge field $\omega(y^-, y^+)$ of general form

$$\omega(y^-, y^+) * \mathcal{P} = \mathcal{P} \int_{u,v} e^{iuv} \omega(2y^- + 2v, u), \quad (3.24a)$$

$$\mathcal{P} * \omega(y^-, y^+) = \mathcal{P} \int_{u,v} e^{iuv} \omega(-u, 2y^+ + 2v). \quad (3.24b)$$

We see that the result splits into the form of a function of y^- or a function of y^+ . This is how it happens, e.g., at the lowest order

$$\Upsilon(\omega, C)|_{C=C_0} \sim \omega(y^-, y^+) * \mathcal{P} - \mathcal{P} * \omega(-y^+, y^-). \quad (3.25)$$

Let us now determine the global symmetry of the vacuum (3.14), (3.15) with $\nu_2 = 0$. The corresponding global symmetry parameter of Eqs. (2.2) satisfies (see [73])

$$d_x \epsilon + [W_0, \epsilon]_* = 0, \quad (3.26a)$$

$$d_z \epsilon + [\Lambda[C_0], \epsilon]_* = 0, \quad (3.26b)$$

where $\Lambda[C_0]$ is defined in the vacuum (3.15) via (2.3), and W_0 is given in (3.14). The global space-time symmetry ϵ can be found in perturbations in ν from (3.26)

$$\epsilon = \epsilon_0 + \nu \epsilon_1 + \dots \quad (3.27)$$

Naturally, one expects ϵ_0 to be bilinear in Y 's and z -independent. It is not difficult to show that the following parameter solves (3.26a):

$$\epsilon_0 = \xi_P^{\alpha\beta} P_{\alpha\beta} + \xi_L^{\alpha\beta} L_{\alpha\beta}, \quad (3.28)$$

where P and L are the Poincaré generators from (3.11), while $\xi_L^{\alpha\beta}$ are arbitrary constants associated with the 3D Lorentz boosts, and

$$\xi_P^{\alpha\beta} = -\frac{3i}{4z} (\xi_0^{\alpha\beta} + \xi_L^{\alpha\gamma} x_\gamma^\beta + \xi_L^{\beta\gamma} x_\gamma^\alpha) \quad (3.29)$$

contains constant parameters $\xi_0^{\alpha\beta}$ associated with the 3D translations. The result presented in (3.28), however, does not satisfy (3.26b), because $[\Lambda, \epsilon_0]_* \neq 0$. This induces a nonzero $O(\nu)$ -correction to ϵ satisfying

$$\nu d_z \epsilon_1 = -[\Lambda[C_0], \epsilon_0]_*. \quad (3.30)$$

The latter could be solved using the standard contracting homotopy⁹ with the result being

$$\epsilon_1 = 8z \xi_L^{\alpha\beta} z_\alpha z_\beta \int_0^1 d\tau \tau (1 - \tau) e^{i\tau z y^+}. \quad (3.31)$$

⁹Whenever consistent, equation of the form $d_z f(z) = dz^\alpha X_\alpha(z)$ can be solved by $f = z^\alpha \int_0^1 d\tau X_\alpha(\tau z)$, known as contracting homotopy.

It can be verified now by a straightforward computation that

$$[\epsilon_1, \Lambda[C_0]]_* = 0. \quad (3.32)$$

Notice that the dependence on oscillators $z, y, \bar{y}$ in (3.31) is exactly the same as in the $\Delta = 2$ connection corrections to Ω in (3.14). This entails ϵ_1 from (3.31) satisfies (see (A21a) and (A23) for a very similar analysis)

$$d_x \epsilon_1 + [W_0, \epsilon_1]_* = 0. \quad (3.33)$$

Therefore, the perturbation series (3.27) terminates at first order in ν that makes

$$\epsilon = \epsilon_0 + 8\nu z \xi_L^{\alpha\beta} z_\alpha z_\beta \int_0^1 d\tau \tau (1 - \tau) e^{i\tau z y^+} \quad (3.34)$$

an exact solution of Eq. (3.26). Thus, the leftover global symmetry is indeed generated by the boundary Poincaré algebra with parameters ξ_L and ξ_P . It can be shown that no other generators from (3.11) are the symmetries of the vacuum. Indeed, the full form of the global symmetry is determined perturbatively from knowing ϵ_0 of (3.27). The lowest order in ν consistency of Eq. (3.26b) implies

$$\delta_{\epsilon_0} C_0 = -\epsilon_0 * C_0 + C_0 * \pi(\epsilon_0) = 0. \quad (3.35)$$

It is not difficult to make sure that only the generators from (3.28) fulfill the condition (3.35).

As a side remark, it is of interest to note that corrections (A23) and (3.31) coincide. Technically, this occurs due to a nice relationship between the two vacuum branches (3.19) through the Poincaré algebra. This observation might have implications for the analysis of the $\Delta = 2$ branch, which we leave for future investigation.

IV. LINEARIZATION

Having settled with the vacuum, one can address the problem of linear fluctuations about it. Our choice of interest is (3.20) and, therefore, the vacuum fields are

$$W_0 := \Omega, \quad (4.1a)$$

$$C_0 := \nu z e^{y\bar{y}}, \quad (4.1b)$$

$$\Lambda_0 := \Lambda[C_0] = \nu z d z^\alpha z_\alpha \int_0^1 d\tau \tau e^{i\tau z y^+}. \quad (4.1c)$$

Linearization of the unfolded HS equations (1.4)

$$C = C_0 + \mathcal{C}, \quad \omega = \Omega + \mathbf{w} \quad (4.2)$$

amounts to

$$d_x \mathbf{w} + \{\Omega, \mathbf{w}\}_* = \sum_{n>0} \mathcal{V}_n(\Omega, \mathbf{w}, C_0^n) + \sum_{n>0} \mathcal{V}_n(\Omega, \Omega, \mathcal{C}, C_0^{n-1}), \quad (4.3a)$$

$$d_x \mathcal{C} + \mathbf{w} C_0 - C_0 * \pi(\mathbf{w}) + \Omega * \mathcal{C} - \mathcal{C} * \pi(\Omega) = \sum_{n>1} \Upsilon_n(\mathbf{w}, C_0^n) + \sum_{n \geq 1} \Upsilon_{n+1}(\Omega, \mathcal{C}, C_0^n), \quad (4.3b)$$

where, abusing notation, we denote, say, $\mathcal{V}(\Omega, \mathbf{w}, C_0, \dots, C_0) := \mathcal{V}_n(\Omega, \mathbf{w}, C_0^n)$. Equivalently, the right-hand sides of Eq. (4.3) can be approached by discarding nonlinear terms in the generating system (2.2) around (4.1). The decomposition takes the form

$$d_x W + \{\Omega, W\}_* = 0, \quad (4.4a)$$

$$d_z W + \{\Lambda_0, W\}_* + \{\Lambda, \Omega\}_* + d_x \Lambda = 0, \quad (4.4b)$$

$$d_x \mathcal{C} + \Omega * \mathcal{C} - \mathcal{C} * \pi(\Omega) + (W(z'; y, \bar{y}) * C_0 - C_0 * W(z'; -y, \bar{y}))|_{z'=-y} = 0. \quad (4.4c)$$

Here, by W and $\mathcal{C}$ we denote fluctuations around Ω and C_0 , correspondingly, and

$$\pi(\Omega(y, \bar{y})) = \Omega(-y, \bar{y}). \quad (4.5)$$

As usually, the connection Λ is expressed via the z -independent $\mathcal{C}(y, \bar{y})$ as follows:

$$\Lambda := \Lambda[\mathcal{C}] = dz^\alpha z_\alpha \int_0^1 d\tau \tau \mathcal{C}(-\tau z, \bar{y}) e^{i\tau z y}. \quad (4.6)$$

Although it may appear unnecessary due to the availability of all vertices in (4.3) from (2.13) and (2.16), analyzing the generating Eq. (4.4) reveals structures that are not immediately apparent from (2.13) and (2.16). Therefore, we proceed using (4.4).

A. Gauge fields

Gauge fields describing linear fluctuations around the background Ω are collected in $\mathbf{w} = \mathbf{w}(y, \bar{y})$ according to (4.2). The same function of two variables y and $\bar{y}$ should appear in the process of reconstruction of z dependence using Eq. (4.4). An important comment in this regard is now in order. The standard case of the free HS fields propagating on AdS corresponds to $\nu = 0$, where $C_0 = \Lambda_0 = 0$. In this case, Eq. (4.4b) lacks the second term. The equation restores the z -dependence of the field W up to a freedom parametrized by the kernel of the operator d_z , which is simply z -independent functions. This way the physical field $\omega(y, \bar{y}) = \Omega + \mathbf{w}$ appears at the zeroth order as a solution of $d_z W = 0$, where the background part

associated with Ω is conventionally separated. For $\nu \neq 0$ the role of the operator d_z is replaced with

$$\mathcal{D}_\nu = d_z + \{\Lambda_0, \bullet\}_*, \quad (4.7)$$

while the physical field, which we now denote with $\mathcal{W}$, satisfies

$$\mathcal{D}_\nu \mathcal{W} = 0. \quad (4.8)$$

Indeed, now that $\nu \neq 0$, the reconstruction of the field W in terms of $\mathcal{C}$ (hidden in Λ) from (4.4b) is carried out up to a solution of the homogeneous Eq. (4.8). Since the operator $\mathcal{D}_\nu$ contains manifestly variable z , solutions of (4.8) are not generally z independent. Nevertheless, the space of solutions of (4.8) should be parametrized by an arbitrary function $\mathbf{w}(y, \bar{y})$ in accordance with Eq. (1.2) which follow from the generating system (4.4).

Let us analyze Eq. (4.8) under the assumption that $\mathcal{W}$ is analytic in ν . In this case, one can elaborate on a perturbation theory in ν .

$$\mathcal{W} = \mathcal{W}^{(0)} + \nu \mathcal{W}^{(1)} + \nu^2 \mathcal{W}^{(2)} + \dots \quad (4.9)$$

Feeding this into (4.8), at the lowest order, we have that

$$d_z \mathcal{W}^{(0)} = 0 \Rightarrow \mathcal{W}^{(0)} = \mathcal{W}^{(0)}(y, \bar{y}). \quad (4.10)$$

At the next $O(\nu)$ order, we further have

$$\nu d_z \mathcal{W}^{(1)} + \{\Lambda_0, \mathcal{W}^{(0)}\}_* = 0. \quad (4.11)$$

The latter equation is generally inconsistent unless

$$d_z \{\Lambda_0, \mathcal{W}^{(0)}\}_* = 0, \quad (4.12)$$

which, using (2.4), reduces to

$$\mathcal{W}^{(0)} * C_0 - C_0 * \pi(\mathcal{W}^{(0)}) = 0. \quad (4.13)$$

The fact that $\mathcal{W}^{(0)}$ is not an arbitrary function of y and $\bar{y}$ may seem to be in tension with $\mathbf{w}(y, \bar{y})$ from (4.2) being arbitrary. Notice, however, that the latter should be encoded in the full solution of (4.8) rather than its perturbative part.

It turns out there is a z independent solution of (4.8) that contains part of the full degrees of freedom. It can be approached as follows. Using that C_0 is proportional to the Fock projector (3.21) and that

$$\pi(y^\pm) = -y^\mp \quad (4.14)$$

it follows from (3.23) that any function of the form

$$\mathcal{W}^{(0)} = \mathcal{W}^{(0)}(y^+) \quad (4.15)$$

solves (4.13). Additionally, such functions enjoy

$$\{\Lambda_0, \mathcal{W}^{(0)}(y^+)\}_* = 0 \quad (4.16)$$

as follows after straightforward calculation. Therefore, for functions of y^+ , the perturbation theory in ν terminates at the first step, as any function $\mathbf{w} = \mathbf{w}(y^+)$ satisfies

$$\mathcal{W}(y, \bar{y}) := \mathbf{w}(y^+), \quad \mathcal{D}_\nu \mathbf{w}(y^+) = 0. \quad (4.17)$$

We can conclude that $\mathbf{w}(y^+)$ represents physical fluctuations and we choose them as a particular solution for $\mathcal{W}$. However, these functions do not encompass all degrees of freedom. Indeed, the physical degrees of freedom are packed into an arbitrary function $\mathbf{w}(y^+, y^-)$ instead of $\mathbf{w}(y^+)$. In the $\nu \neq 0$ case, the missing degrees of freedom are embedded in the solutions of (4.8), which typically depend on z . In our analysis of the broken phase, we focus on the z -independent degrees of freedom. These are functions of the form $\mathbf{w}(y^+)$. Below we briefly discuss how the rest of the degrees of freedom arise as well as exclude certain seemingly natural z -independent candidates.

B. Unaccounted degrees of freedom

It was already stated that Eq. (4.17) is not a general analytic solution of the Eq. (4.8). For instance, functions of the form

$$\mathcal{W}^{(0)} = y_\alpha^+ * \phi^{\alpha\beta}(y, \bar{y}) * y_\beta^+, \quad (4.18)$$

where ϕ is arbitrary, they still meet the integrability condition given by (4.13). Since (4.18) generally no longer anticommutes with Λ_0 , the field $\mathcal{W}^{(1)}$ becomes dependent on z . This process continues beyond this point, leading to the generation of $\mathcal{W}^{(2)}$ and so forth.

One might wonder what the other solutions of (4.8) are? In particular, there could be nonanalytic solutions in ν for which the decomposition (4.9) does not apply. Even among ν -analytic and z -independent functions, it is possible that some solutions have been overlooked. This brings us back to (4.13). Aside from functions that are annihilated by the Fock projector, Eq. (4.13) is satisfied for even functions of the form

$$f(y\bar{y}) = f(-y\bar{y}). \quad (4.19)$$

This is simply a consequence of the fact that C_0 itself is a function of $y\bar{y}$, and for even functions, we have $\pi f(y\bar{y}) = f(y\bar{y})$. Assuming such functions solve in addition (4.8), we observe that they have to be star-product periodic. Indeed, from the vacuum equation

$$d_z \Omega + \{\Lambda_0, \Omega\}_* + d_x \Lambda_0 = 0 \quad (4.20)$$

and (4.1c) it follows from the dz -sector that

$$[D, \Lambda_0]_* = \Lambda_0, \quad (4.21)$$

where D is the dilatation operator defined in (3.11d). Therefore, denoting

$$f(y\bar{y}) := F_*(D), \quad (4.22)$$

where $F_*(D)$ is a star-product series in D and using that¹⁰

$$\mathcal{D}_\nu f = [f, \Lambda_0]_* = 0, \quad (4.23)$$

along with (4.21), we have

$$F_*(D) = F_*(D - 1). \quad (4.24)$$

The latter implies

$$F_*(D) = \sum_n a_n \exp_*(2\pi i n D), \quad (4.25)$$

where a_n are arbitrary numbers. In the Appendix E, we demonstrate that although functions F_* formally exist, the period of these is such that their symbols are not analytic in the variable $y\bar{y}$, which means they should be disregarded.

C. Linearizing with $\mathbf{w}(y^+)$

Let us emphasize that we do not have the complete set of solutions of (4.8). In our approach, we consider only $\mathbf{w}(y^+)$ as the physical cohomologies for the fluctuating 1-forms. While it is generally inconsistent to restrict HS modules to submodules at the level of equations, it turns out that $\mathbf{w}(y^+)$ constitutes a closed sector in the broken phase, at least at the linearized level, as we will demonstrate.

The choice of the physical 1-forms restricted by $\mathbf{w}(y^+)$ strongly constrains the form of the HS vertices and sets constraints on the Weyl module $\mathcal{C}$. Specifically, the solution of (4.4b) for the 1-form master field W is now organized as follows:

$$W = \mathbf{w}(y^+) + W'[\Omega, \mathcal{C}, C_0](z; Y) + W''[\mathbf{w}, C_0](z; Y), \quad (4.26)$$

where the first term is z -independent physical gauge field, representing a part of the freedom in homogeneous solutions of (4.4b), the second contains z -dependent corrections expressed in terms of the background fields and the 0-form $\mathcal{C}$, while the third term contains a contribution of the propagating 1-form $\mathbf{w}$. However, the latter cannot appear because the contribution containing $\mathbf{w}$ drops off from (4.4b),

¹⁰Since it is not important for the following, below we take f as a space-time 0-form. This explains presence of the commutator instead of the anticommutator.

$$\{\mathbf{w}(y^+), \Lambda_0\}_* = 0 \Rightarrow W''[\mathbf{w}, C_0] = 0. \quad (4.27)$$

This implies that not every structure on the right-hand side of (4.3a) is actually present. Indeed, the first term on the right comes from the third term in (4.26) upon substitution into the anticommutator of (4.4a) followed by setting $z = 0$. Since $W'' = 0$, such contribution should be equal to zero. Analogously, the first term on the right of (4.3b) should be absent. From the point of view of the HS vertices (2.16), the latter statement is a quite nontrivial one and we double-check it by a direct calculation in the Appendix C. Additionally, Eq. (3.23) implies that

$$\mathbf{w}C_0 - C_0 * \pi(\mathbf{w}) = 0. \quad (4.28)$$

Eventually, the system (4.3) takes a simpler form

$$d_x \mathbf{w} + \{\Omega, \mathbf{w}\}_* = \sum_n \mathcal{V}_n(\Omega, \Omega, \mathcal{C}, C_0^{n-1}), \quad (4.29a)$$

$$d_x \mathcal{C} + \Omega * \mathcal{C} - \mathcal{C} * \pi(\Omega) = \sum_n \Upsilon_n(\Omega, \mathcal{C}, C_0^n). \quad (4.29b)$$

In general, omitting certain terms from the unfolded equations leads to inconsistencies. In our case, the restriction on cohomology, given by $\mathbf{w}(y, \bar{y}) = \mathbf{w}(y^+)$, arises from our choice of solutions to the Eq. (4.4b). This should impose a constraint on the module $\mathcal{C}$, which is yet to be determined.

A further simplification of the system (4.3) arises from the fact that Ω (3.9) is no more than quadratic in y . Examining Eq. (2.13) with Ω in place of ω , we observe that its derivatives become zero for $n > 2$. Consequently, the right-hand side of (4.29a) also vanishes for $n > 2$. In fact, it also vanishes for $n = 2$, because $\partial_\alpha \partial_\beta \Omega(y, \bar{y}) \wedge \partial^\alpha \partial^\beta \Omega(y', \bar{y}') = 0$. As a result, the sum on the right of (4.29a) contains only one contribution corresponding to $n = 1$. A similar analysis regarding the derivatives acting on Ω in (2.16) leads us to conclude that only $n = 1$ and $n = 2$ can contribute to the right-hand side of (4.29b). Thus, Eq. (4.3) dramatically simplify

$$d_x \mathbf{w} + \{\Omega, \mathbf{w}\}_* = \mathcal{V}(\Omega, \Omega, \mathcal{C}), \quad (4.30a)$$

$$d_x \mathcal{C} + \Omega * \mathcal{C} - \mathcal{C} * \pi(\Omega) = \Upsilon(\Omega, \mathcal{C}, C_0) + \Upsilon(\Omega, \mathcal{C}, C_0, C_0), \quad (4.30b)$$

Now we only need to calculate the lowest vertices on the right-hand sides.

D. Vertices: Explicit form

Here we compute the manifest form of Eq. (4.30).

Vertex $\mathcal{V}(\Omega, \Omega, \mathcal{C})$ This vertex is given by a well-known expression from the central on-mass-shell theorem [21]. Naturally, it can be obtained from (2.13) for $n = 1$ by substituting (3.9) in place of ω with the final result being

$$\begin{aligned} \mathcal{V}(\Omega, \Omega, \mathcal{C}) &= -\mathbf{e}_\alpha{}^\alpha \wedge \mathbf{e}^{\alpha\beta} \partial_\alpha \partial_\beta \mathcal{C}(0, \bar{y}) \\ &= -\frac{1}{4z^2} (2i dx^{\alpha\beta} \wedge dz + dx_\gamma{}^\alpha \wedge dx^{\beta\gamma}) \bar{\partial}_\alpha \bar{\partial}_\beta \mathcal{C}(0, \bar{y}), \end{aligned} \quad (4.31)$$

where $\mathbf{e}$ is the vierbein 1-form from (3.5c).

Notice that the left-hand side of Eq. (4.30a) does not match the right-hand side given by Eq. (4.31). Specifically, while $\mathbf{w}$ depends on the variable y^+ , the vertex described in (4.31) depends on $\bar{y}$. This mismatch arises because the restrictions imposed on physical fields by Eq. (4.8) lead to a specific constraint on the Weyl module $\mathcal{C}(y, \bar{y})$ through the integrability condition for (4.3b). We will identify this constraint in the following discussion, from which it follows that

$$\mathcal{C}(0, \bar{y}) = C_0 + \bar{y}^\alpha C_\alpha + \frac{1}{2} \bar{y}^\alpha \bar{y}^\beta C_{\alpha\beta}, \quad (4.32)$$

where the components C_0 , C_α , and $C_{\alpha\beta}$ are $\bar{y}$ -independent and correspond to fields of helicities 0, $-\frac{1}{2}$ and -1 , respectively, as stated in Eq. (2.12b). Notice that $\mathcal{C}(0, \bar{y})$ cuts short at negative helicity $s = -1$. Plugging (4.32) into (4.31), we obtain

$$\mathcal{V}(\Omega, \Omega, \mathcal{C}) = -\frac{1}{4z^2} (2i dx^{\alpha\beta} \wedge dz + dx_\gamma{}^\alpha \wedge dx^{\beta\gamma}) C_{\alpha\beta}, \quad (4.33)$$

which is Y -independent and captures only the helicity $s = -1$ encoded in the self-dual Maxwell tensor $C_{\alpha\beta}$.

Vertex $\Upsilon(\Omega, \mathcal{C}, C_0)$ This vertex comes from the linearization $\mathcal{C} \rightarrow C_0 + \mathcal{C}$ of the vertex $\Upsilon(\Omega, \mathcal{C}, C)$. The latter is known in the literature; see [33] (specialized to the self-dual case). We reproduce the same expression in a slightly different form using (2.16) with $n = 2$ (see also [55])

$$\begin{aligned} \Upsilon(\Omega, \mathcal{C}, C) &= iy^\alpha \int_{\mathcal{D}_2^{[0]}} e^{iuv} \partial_\alpha \Omega(S_2^{[0]} y + v, \bar{y}) \star C(\xi_1 y - \eta_1 u, \bar{y}) \star C(\xi_2 y - \eta_2 u, \bar{y}) \\ &\quad - iy^\alpha \int_{\mathcal{D}_2^{[1]}} e^{iuv} C(\xi_1 y - \eta_1 u, \bar{y}) \star \partial_\alpha \Omega(S_2^{[1]} y + v, \bar{y}) \star C(\xi_2 y - \eta_2 u, \bar{y}) \\ &\quad + iy^\alpha \int_{\mathcal{D}_2^{[2]}} e^{iuv} C(\xi_1 y - \eta_1 u, \bar{y}) \star C(\xi_2 y - \eta_2 u, \bar{y}) \star \partial_\alpha \Omega(S_2^{[2]} y + v, \bar{y}), \end{aligned} \quad (4.34)$$

where the integration over u and v is implicitly assumed as in (2.16), while ∂ differentiates the first argument of Ω . Using (3.9) and that $\mathcal{D}_2^{[0]} \sqcup \mathcal{D}_2^{[2]} = \mathcal{D}_2^{[1]}$, (2.19), the integration over u and v can be completed. Connection Ω consists of linear and bilinear in y parts. Direct calculation shows that the bilinear part contribution vanishes, which is also due to the structure of $S_n^{[k]}$; see (2.18). Eventually, Eq. (4.34) can be shuffled into the following form:

$$\begin{aligned} \Upsilon(\Omega, \mathcal{C}, C_0) &:= \Upsilon(\Omega, C, C)|_{C=C_0+\mathcal{C}} \\ &= i\nu z e^{\alpha\beta} y_\alpha \int_0^1 d\tau \tau e^{\tau y \bar{y}} ((1-\tau)y_\beta - \bar{\partial}_\beta)(\mathcal{C}((1-\tau)y, \bar{y} - i\tau y) - \mathcal{C}((1-\tau)y, \bar{y} + i\tau y)), \end{aligned} \quad (4.36)$$

where the integration over $\mathcal{D}_2^{[0]}$ has been reduced to the one-dimensional over τ using

$$\int_{\mathcal{D}_2^{[0]}} f(\xi_1, \xi_2) = \int_0^1 d\tau (1-\tau) f(\tau, 1-\tau). \quad (4.37)$$

Recall also that $e^{\alpha\beta} := e^{\alpha\beta} \delta_\beta^\beta$.

Vertex $\Upsilon(\Omega, \mathcal{C}, C_0, C_0)$ Similarly to the previous case, this vertex follows from the linearization of $\Upsilon(\Omega, C, C, C)$. However, the vertex is equal to zero as we show now.

$$\begin{aligned} \Upsilon(\Omega, C, C) &= \frac{1}{2} e^{\alpha\beta} y_\alpha \int_{\mathcal{D}_2^{[0]}} [[\bar{y}_\beta, C(\xi_1 y, \bar{y})]_\star, C(\xi_2 y, \bar{y})]_\star \\ &= i e^{\alpha\beta} y_\alpha \int_{\mathcal{D}_2^{[0]}} [\bar{\partial}_\beta C(\xi_1 y, \bar{y}), C(\xi_2 y, \bar{y})]_\star, \end{aligned} \quad (4.35)$$

It is straightforward to linearize the above expression about (4.1b) with the result being

Indeed, from (2.16) it follows that the vertex contains $(y^\alpha \partial_\alpha)^2 \Omega(S_3^{[k]} y + u, \bar{y})$, which is, thanks to the fact that Ω is bilinear in y , leads to the following u and S independent piece:

$$\hat{\Omega} := (y^\alpha \partial_\alpha)^2 \Omega(S_3^{[k]} y + u, \bar{y}) = \frac{1}{4z} y^\alpha y^\beta dx_{\alpha\beta}. \quad (4.38)$$

This allows us to complete the integration over u and v in (2.16) and gives us

$$\begin{aligned} \Upsilon(\Omega, C, C, C) &= (-i)^2 \hat{\Omega} \cdot \left(\int_{\mathcal{D}_3^{[0]}} C(\xi_1 y, \bar{y}) \star C(\xi_2 y, \bar{y}) \star C(\xi_3 y, \bar{y}) - \int_{\mathcal{D}_3^{[1]}} C(\xi_1 y, \bar{y}) \star C(\xi_2 y, \bar{y}) \star C(\xi_3 y, \bar{y}) \right. \\ &\quad \left. + \int_{\mathcal{D}_3^{[2]}} C(\xi_1 y, \bar{y}) \star C(\xi_2 y, \bar{y}) \star C(\xi_3 y, \bar{y}) - \int_{\mathcal{D}_3^{[3]}} C(\xi_1 y, \bar{y}) \star C(\xi_2 y, \bar{y}) \star C(\xi_3 y, \bar{y}) \right). \end{aligned} \quad (4.39)$$

Now, the property of the integration domain (2.19), which in this case reads $\mathcal{D}_3^{[0]} \sqcup \mathcal{D}_3^{[2]} = \mathcal{D}_3^{[1]} \sqcup \mathcal{D}_3^{[3]}$ makes (4.39) identically vanish. So, we conclude that

$$\Upsilon(\Omega, C, C, C) = 0 \Rightarrow \Upsilon(\Omega, \mathcal{C}, C_0, C_0) = 0. \quad (4.40)$$

Let us summarize our results on the free field equations obtained at this point. As follows from the above computations, the linear system (4.30) is further reduced. In particular, it lacks $O(\nu^2)$ contribution represented by the last term in (4.3b). The $O(\nu)$ contribution is given by (4.36), while the gauge sector (4.3a) contains no ν -dependent terms at all

$$d_x \mathbf{w} + \{\Omega, \mathbf{w}\}_\star = -\mathbf{e}_\alpha^{\dot{\alpha}} \wedge \mathbf{e}^{\alpha\beta} \partial_\alpha \partial_\beta \mathcal{C}(0, \bar{y}) = -\mathbf{e}_\alpha^{\dot{\alpha}} \wedge \mathbf{e}^{\alpha\beta} \mathcal{C}_{\alpha\beta}, \quad (4.41a)$$

$$d_x \mathcal{C} + \Omega \star \mathcal{C} - \mathcal{C} \star \pi(\Omega) = \Upsilon(\Omega, \mathcal{C}, C_0). \quad (4.41b)$$

The source for the gauge fields on the right side of Eq. (4.41a) is zero for all helicities except for $s = -1$. As a result, for nonpositive helicities we are left with only one gauge field of $s = -1$, along with matter fields of spins $s = 0$ and chiral $s = -\frac{1}{2}$, (4.32).

Consistency Consistency of the system (4.41) is not guaranteed despite the original Eq. (2.2) from which it comes being consistent. The reason is a restriction set on the physical field (4.17), which results in certain vertex structures vanishing. Therefore, we need to check if (4.41) respects integrability $d_x^2 = 0$.

Applying d_x to (4.41a) introduces no new constraints, confirming its consistency. The proof is relatively straightforward; it involves substituting $d_x \mathcal{C}_{\alpha\beta}$ from (4.41b), and notably, no contributions from $\Upsilon(\Omega, \mathcal{C}, C_0)$ (4.36) appear during this process. However, the consistency of (4.41b) is not immediately obvious. In fact, (4.41b) will only be consistent if the condition (4.32) is satisfied. Since the proof is quite technical, we have included it in the Appendix D.

V. DUAL FORMULATION

Klebanov and Polyakov conjectured holographic duality between Vasiliev's HS theory and conformal $O(N)$ models. The basis of the conjectured duality is the fundamental result of Flato and Fronsdal, who showed that an infinite tower of the $4d$ massless fields can be viewed as tensor products of $3d$ singletons [76]. The map between the AdS and conformal fields is particularly simply realized using the unfolded approach at the level of equations of motion, as demonstrated in [77]. The natural question we ask here is how the Flato-Fronsdal result modifies in the symmetry-broken phase. To this end, let us first recall the derivation in the unbroken phase with $\nu = 0$ following [77].

A. Symmetry unbroken case: $\nu = 0$

Since field degrees of freedom are collected in the 0-form sector, we consider Eq. (4.41b) with $\nu = 0$

$$d_x \mathcal{C}_{\nu=0} + \Omega * \mathcal{C}_{\nu=0} - \mathcal{C}_{\nu=0} * \pi(\Omega) = 0, \quad (5.1)$$

where by $\mathcal{C}_{\nu=0}$ we denoted the standard twisted-adjoint module corresponding to (4.41b) with vanishing right-hand side. Substituting (3.9) and using (2.8), one arrives at

$$d_x \mathcal{C}_{\nu=0} + \frac{i}{2z} dx^{\alpha\beta} (y - \bar{\partial})_\alpha (\bar{y} + \partial)_\beta \mathcal{C}_{\nu=0} = 0, \quad (5.2a)$$

$$\frac{\partial}{\partial z} \mathcal{C}_{\nu=0} + \frac{1}{2z} (y\bar{y} - \partial\bar{\partial}) \mathcal{C}_{\nu=0} = 0, \quad (5.2b)$$

where the first equation of (5.2) describes the evolution of the Weyl module along a three-dimensional AdS slice, while the second—its dependence on the radial direction. The Flato-Fronsdal correspondence can be approached by introducing the intertwining of the Weyl module with the current module T as follows:

$$\mathcal{C} = ze^{y\bar{y}} T(w, \bar{w} | \vec{x}, z), \quad w = \sqrt{z}y, \quad \bar{w} = \sqrt{z}\bar{y}. \quad (5.3)$$

We will use the same map for arbitrary ν because the background geometry is AdS. Notice the presence of the vacuum (4.1b) in the definition (5.3). In terms of the current module T , the system (5.2) reduces to

$$d_x T_{\nu=0} - \frac{i}{2} dx^{\alpha\beta} \partial_\alpha \bar{\partial}_\beta T_{\nu=0} = 0, \quad (5.4a)$$

$$\frac{\partial}{\partial z} T_{\nu=0} - \frac{1}{2} \partial\bar{\partial} T_{\nu=0} = 0. \quad (5.4b)$$

Here ∂ and $\bar{\partial}$ denote differentiation with respect to the spinorial argument in both (5.2) and (5.4), e.g., $\partial_\alpha \mathcal{C} := \frac{\partial}{\partial y^\alpha} \mathcal{C}$, $\bar{\partial}_\alpha T := \frac{\partial}{\partial \bar{w}^\alpha} T$, while $\frac{\partial}{\partial z}$ differentiates the manifest dependence on z ; in particular, $\frac{\partial}{\partial z} w = 0$. Notice that manifest dependence on z completely decouples from

(5.4). Equation (5.4a) describes a set of conserved $3d$ currents

$$\frac{\partial}{\partial x^{\alpha_1 \alpha_2}} j^{\alpha_1 \dots \alpha_s} = 0, \quad \frac{\partial}{\partial x^{\alpha_1 \alpha_2}} \bar{j}^{\alpha_1 \dots \alpha_s} = 0, \quad (5.5)$$

which are associated with coefficients in the decomposition of $j(w) := T(w, 0)$ and $\bar{j}(\bar{w}) := T(0, \bar{w})$. It also describes a primary of conformal dimension $\Delta = 1$, $j_0 = T(0, 0)$, and a primary of conformal dimension $\Delta = 2$, $\bar{j}_0 := \partial\bar{\partial} T(w, \bar{w})|_{w=\bar{w}=0}$. These appear as $H^0(\sigma^-)$ -cohomologies, where

$$\sigma^- = dx^{\alpha\beta} \frac{\partial}{\partial w^\alpha} \frac{\partial}{\partial \bar{w}^\beta}. \quad (5.6)$$

The Flato-Fronsdal decomposition then arises as

$$T_{\nu=0} = \sum_i C_+^i(w^+) C_-^i(w^-), \quad w_\alpha^\pm = w_\alpha \pm i\bar{w}_\alpha, \quad (5.7)$$

where $C_\pm^i$ are subject to the following condition:

$$d_x C_\pm^i \pm \frac{1}{2} dx^{\alpha\beta} \partial_\alpha \bar{\partial}_\beta C_\pm^i = 0. \quad (5.8)$$

It is straightforward to verify that (5.4a) is satisfied for (5.7), provided (5.8) is imposed. The latter just describes free massless scalars on the $3d$ Minkowski background

$$\square \varphi_\pm^i = 0, \quad \varphi_\pm^i := C_\pm^i(0|x). \quad (5.9)$$

B. Symmetry broken case: $\nu \neq 0$

Now we are interested in how Eq. (5.4) are modified in the broken phase with $\nu \neq 0$. To see this, we use the field-current correspondence (5.3) and substitute it into (4.41b) using (4.36). After simple algebra, we arrive at the following final result:

$$d_x T - \frac{i}{2} dx^{\alpha\beta} \partial_\alpha \bar{\partial}_\beta T = \frac{i\nu}{2} dx^{\alpha\beta} w_\alpha \bar{\partial}_\beta \int_0^1 d\tau (1-\tau) (T^- - T^+), \quad (5.10a)$$

$$\frac{\partial}{\partial z} T - \frac{1}{2} \partial\bar{\partial} T = -\frac{\nu}{2} w^\alpha \bar{\partial}_\alpha \int_0^1 d\tau (1-\tau) (T^- - T^+), \quad (5.10b)$$

where

$$T^\pm = T(\tau w, \bar{w} \pm i(1-\tau)w). \quad (5.11)$$

Notice that the factor $\exp y\bar{y}$ in (5.3), as well as manifest dependence on z , decouples from (5.10). Thus, one indeed arrives at the dual formulation of the on-shell $4D$ system via the $3D$ off-shell given by (5.10). The crucial question, of course, is its consistency. As we stated earlier, the

original equations (4.41b) are generally inconsistent, unless the Weyl module $\mathcal{C}$ is constrained by (4.32). The latter condition imposes a constraint on T of the form

$$T(0, \bar{w}) = T_0 + \bar{w}^\alpha T_\alpha + \frac{1}{2} \bar{w}^\alpha \bar{w}^\beta T_{\alpha\beta}. \quad (5.12)$$

In the Appendix D, we check that (5.12) indeed follows from $d_x^2 = \{d_x, d_z\} = 0$. Constraint (5.12), which can be reformulated as

$$\left(\frac{\partial}{\partial \bar{w}}\right)^3 T(0, \bar{w}) = 0, \quad (5.13)$$

generates a secondary constraint from

$$d_x \left(\frac{\partial}{\partial \bar{w}}\right)^3 T(0, \bar{w}) = \left(\frac{\partial}{\partial \bar{w}}\right)^3 d_x T(0, \bar{w}) = 0, \quad (5.14)$$

and so forth. It is not difficult to identify them all by noting that at $w = 0$ Eq. (5.10a) amounts to conservation of chiral currents encoded in

$$d_x T(0, \bar{w}) - \frac{i}{2} dx^{\alpha\beta} \partial_\alpha \bar{\partial}_\beta T(w, \bar{w})|_{w=0} = 0. \quad (5.15)$$

Constraint (5.12) then implies that the helicity- s current modules T_s have to vanish for $s < -1$,

$$T_{s<-1} = 0, \quad (5.16)$$

where

$$(w^\alpha \partial_\alpha - \bar{w}^\alpha \bar{\partial}_\alpha) T_s = 2s T_s. \quad (5.17)$$

Notice that the whole module T splits into a direct sum

$$T = \bigoplus_s T_s, \quad s = 0, \pm \frac{1}{2}, \pm 1, \dots, \quad (5.18)$$

while (5.12) factors out a set of submodules $T_{s<-1}$, keeping the rest $T_{s \geq -1}$ alive.

Primaries Equation (5.10a) is supposed to describe the broken phase of the current conservation condition. In the unbroken case, the conserved currents (5.5) arise as the following consequence of (5.4a):

$$\frac{\partial}{\partial x_{\alpha\beta}} \frac{\partial}{\partial w^\alpha} \frac{\partial}{\partial w^\beta} j(w) = \frac{\partial}{\partial x_{\alpha\beta}} \frac{\partial}{\partial \bar{w}^\alpha} \frac{\partial}{\partial \bar{w}^\beta} \bar{j}(\bar{w}) = 0, \quad (5.19)$$

where the current primaries are associated with 0-form cohomologies of (5.6)

$$j(w) = T(w, 0), \quad \bar{j}(\bar{w}) = T(0, \bar{w}). \quad (5.20)$$

When $\nu \neq 0$, Eq. (5.4a) is replaced with (5.10a), which we can write down as

$$d_x T(w, \bar{w}) - \frac{i}{2} \sigma_\nu T(w, \bar{w}) = 0, \quad (5.21)$$

where

$$\sigma_\nu T(w, \bar{w}) := dx^{\alpha\beta} \left(\partial_\alpha \bar{\partial}_\beta T(w, \bar{w}) + \nu w_\alpha \bar{\partial}_\beta \right. \\ \left. \times \int_0^1 d\tau (1 - \tau) (T^- - T^+) \right). \quad (5.22)$$

Primary fields cannot be expressed via derivatives of other fields. Thus, those belonging to the kernel of σ_ν are necessarily primaries. We identify them by solving for primary components T^{pr}

$$\sigma_\nu T^{pr}(w, \bar{w}) = 0. \quad (5.23)$$

To do so, we note that (5.23) is equivalent to

$$\bar{\partial}_\beta \psi_\alpha + \bar{\partial}_\alpha \psi_\beta = 0, \quad (5.24)$$

where

$$\psi_\alpha = \partial_\alpha T^{pr} + \nu w_\alpha \int_0^1 d\tau (1 - \tau) (T^{pr-} - T^{pr+}). \quad (5.25)$$

The general solution of (5.24) is

$$\psi_\alpha = \phi_{1\alpha}(w) + \bar{w}_\alpha \phi_2(w), \quad (5.26)$$

where $\phi_{1,2}$ are arbitrary functions. Contracting (5.25) with w^α , we have

$$w^\alpha \partial_\alpha T^{pr} = w^\alpha \phi_{1\alpha}(w) - w \bar{w} \phi_2(w). \quad (5.27)$$

Therefore, T^{pr} itself should be of the following form

$$T^{pr} = j(w) + w \bar{w} f(w) + \bar{j}(\bar{w}), \quad (5.28)$$

where j and f are expressed via ϕ_1 and ϕ_2 , and $\bar{j}$ is arbitrary. Substituting it back to (5.23), it is easy to see that the equation is only satisfied for the following functions:

$$j(w), \quad w \bar{w} \tilde{j}_0, \quad \bar{j}_\alpha \bar{w}^\alpha, \quad (5.29)$$

where $\tilde{j}_0$ and $\bar{j}_\alpha$ do not depend on $w, \bar{w}$. The list of these primaries may not be complete. Specifically, σ_ν does not respect grading as it mixes various components of the module T . As a result, if $\sigma_\nu T \neq 0$, then a combination of several components of T is expressed via a derivative of a single one. Therefore, it is a matter of definition which field from the set generated by σ_ν should be called primary. In particular, the field associated with the quadratic combination of $\bar{w}$ (the helicity $s = -1$ antichiral current),

$$\bar{j}_1(\bar{w}) = \frac{1}{2} \bar{j}_{\alpha\beta} \bar{w}^\alpha \bar{w}^\beta \quad (5.30)$$

can be taken as a primary. Indeed, using (5.22) we find that

$$\sigma_\nu \bar{j}_1(\bar{w}) = \frac{2i\nu}{3} dx_\alpha{}^\gamma \bar{j}_{\gamma\beta} w^\alpha w^\beta \quad (5.31)$$

contributes to the following sector of (5.10):

$$d_x j_{\alpha(2)} - \frac{i}{2} dx^{\beta(2)} T_{\beta\alpha(2),\beta} + \frac{2\nu}{3} dx_\alpha{}^\beta \bar{j}_{\beta\alpha} = 0, \quad (5.32)$$

where we use the notation

$$T(w, \bar{w}) := \sum_{m,n} \frac{1}{m!n!} T_{\alpha(m),\beta(n)} (w^\alpha)^n (\bar{w}^\beta)^n, \\ j_{\alpha(m)} := T_{\alpha(m),\beta(0)}, \quad \bar{j}_{\beta(n)} := T_{\alpha(0),\beta(n)}. \quad (5.33)$$

From (5.32) we see that the field $T_{\beta\alpha(2),\beta}$ is expressed via the derivative of a primary $j_{\alpha(2)}$ and the field $\bar{j}_{\alpha(2)}$. The latter can be chosen as a primary. Given that the module T decomposes into a direct sum (5.18) and in view of (5.16), it is not hard to make sure that the full list of primaries is

$$j(w), \quad w\bar{w}\tilde{j}_0, \quad \bar{j}_\alpha \bar{w}^\alpha, \quad \bar{j}_{\alpha\beta} \bar{w}^\alpha \bar{w}^\beta. \quad (5.34)$$

Component form Using the definition (5.33), let us rewrite (5.10a), (5.10b) in terms of components of T . We can merge the two equations into one via the vierbein (3.5c)

$$d_x T = -ize^{\alpha\beta} (\partial_\alpha \bar{\partial}_\beta T + \nu w_\alpha \bar{\partial}_\beta J[T]), \quad (5.35)$$

where we denote

$$J[T] := \int_0^1 d\tau (1-\tau)(T^- - T^+). \quad (5.36)$$

This form is convenient, because it contains both symmetric and antisymmetric parts of the spinor components on the right-hand side. Substitution of (5.33) gives us

$$d_x T_{\alpha(m),\beta(n)} = -ize^{\gamma\rho} \left(T_{\gamma\alpha(m),\rho\beta(n)} + 4i\nu\epsilon_{\alpha\gamma} \right. \\ \left. \times \sum_{k=1}^{\lfloor \frac{m}{2} \rfloor} \frac{k(-)^k}{m+1} T_{\alpha(m-2k),\alpha(2k-1)\beta(n)\rho} \right). \quad (5.37)$$

In obtaining this result we have not taken into account the consistency condition (5.12), the component form of which is

$$\bar{j}_{\beta(n)} := T_{\alpha(0),\beta(n)} = 0 \quad \text{for all } n > 2. \quad (5.38)$$

This condition sets to zero all the components $T_{\alpha(m),\beta(n)}$ with $n-m > 2$. To see this, one starts with the (5.37) for the $m=0, 1$ cases and finds $T_{\alpha,\beta(n+1)} = 0, T_{\alpha(2),\beta(n+2)} = 0$ for all $n > 2$. The general claim is proven by induction (see Appendix D)

$$T_{\alpha(m+2s),\beta(m)} = 0 \quad \text{for all } s < -1, \quad m+2s \geq 0. \quad (5.39)$$

For the right-hand side of (5.37) the latter implies that the sum is nonzero only if

$$m-4k-n \geq -2 \Rightarrow k \leq \frac{m+2-n}{4}. \quad (5.40)$$

It is convenient to further rewrite (5.37) in terms of the helicity- s modules T^s , (5.18), which means that one simply has to replace indices as follows $m \rightarrow m+2s$ and $n \rightarrow m$. For the 3D part we have

$$d_x T_{\alpha(m+2s),\beta(m)}^s - \frac{i}{2} dx^{\gamma\gamma'} T_{\gamma\alpha(m+2s),\gamma\beta(m)}^s \\ = 2\nu dx^\gamma_\alpha \sum_{k=1}^{\lfloor \frac{s+1}{2} \rfloor} \frac{k(-)^k}{m+2s+1} T_{\alpha(m+2s-2k),\alpha(2k-1)\beta(m)\gamma}^{s-2k} \quad (5.41)$$

where the constraint (5.40) has been taken into account. Let us summarize the main features of Eq. (5.41).

(i) Equation (5.41) acquires the following schematic form:

$$DT^s \sim \nu dx \sum_{s'=-1}^{s-2} T^{s'}, \quad s \geq 1, \quad (5.42)$$

where by D we sloppily denote the action on the module T^s manifested on the left of (5.41). In particular, when $\nu = 0$ the equation $DT^s = 0$ is a standard current-conserving condition (5.4a) for helicity- s field. In the case $\nu \neq 0$ the left-hand side of (5.42) is generally nonzero unless $s-2 < -1$, i.e.,

$$d_x T_{\alpha(m+2s),\beta(m)}^s - \frac{i}{2} dx^{\gamma(2)} T_{\gamma\alpha(m+2s),\gamma\beta(m)}^s \\ = 0 \quad \text{for } s = -1, 0, \pm \frac{1}{2}, \quad \forall \nu \neq 0 \quad (5.43)$$

(ii) If $s \geq 1$ the right-hand side is nonzero, while the s -current j^s no longer conserves in general. Indeed, from (5.41) we have (recall, $j_{\alpha(2s)} := T_{\alpha(2s),\beta(0)}$)

$$d_x j_{\alpha(2s)} - \frac{i}{2} dx^{\gamma(2)} T_{\gamma\alpha(2s),\gamma}^s \\ = 2\nu dx^\gamma_\alpha \sum_{k=1}^{\lfloor \frac{s+1}{2} \rfloor} \frac{k(-)^k}{2s+1} T_{\alpha(2s-2k),\alpha(2k-1)\gamma}^{s-2k} \quad (5.44)$$

From here, we find, after some combinatorial algebra,

$$\frac{\partial}{\partial x^{\beta(2)}} j^{\beta(2)}_{\alpha(2s-2)} = -\nu \sum_{k=1}^{\lfloor \frac{s+1}{2} \rfloor} \frac{(-)^k (s-k)(2k)!}{s(2s-1)} \times T_{\beta\alpha(2s-2k-1),\alpha(2k-1)\gamma}^{s-2k} e^{\beta\gamma}. \quad (5.45)$$

The right-hand side above contains traces of the current modules $T^{s'}$ that depend on the radial coordinate z via (5.10b). This means that these traces are not defined by other currents in accordance with the fact that the global higher-spin symmetry is broken rather than deformed. Therefore, the $s \geq 1$ currents are generally not conserved, with the exception of $s = 1$, for which it follows from (5.45)

$$\frac{\partial}{\partial x^{\alpha\beta}} j^{\alpha\beta}_{s=1} = 0. \quad (5.46)$$

The conservation of the helicity $s = +1$ current has a somewhat kinematical origin. The breaking of symmetry leads to the Eq. (5.42), which exhibits a “Russian doll” structure: the nonconservation of the helicity s current is expressed in terms of currents with helicities ranging from -1 to $s - 2$. For $s = +1$, there is only one contribution from the helicity -1 . The divergence (5.45) is represented by the trace $\bar{j}_{\alpha\beta} e^{\alpha\beta} \equiv 0$, which makes the current conserved (5.46). From a dual perspective, the conservation of the spin-one current suggests that the global $U(1)$ symmetry may persist on the AdS slice even after symmetry breaking.

Comments on $\nu_2 \neq 0$ Let us discuss the possible implications of the nonzero parameter ν_2 present in the vacuum solution (3.14), (3.15). Its presence would affect the linearized analysis in several ways. First, since $\Lambda[C_0]$ in (4.1c) receives an additional contribution from ν_2 , it modifies the equation that defines the physical gauge fields in (4.8). Specifically, the z -independent solutions form a subspace of those with $\nu_2 = 0$, as presented in (4.17). It is reasonable to expect that activating ν_2 leads to a smaller set of gauge fluctuations that decouple from the Weyl module. This is likely to impose a stronger consistency constraint on the Weyl module, which may further reduce the 0-form sector. Nevertheless, since the structure of the Fock projector $e^{\gamma\bar{\gamma}}$ remains present within the ν_2 branch, some gauge fields are still likely to decouple.

More importantly, the nonzero $\Delta = 2$ branch may significantly affect the boundary interpretation. Specifically, the fact that the free equations (4.3b) admit the T -current form (5.10) heavily relies on the structure of the vacuum (3.15) with $\nu_2 = 0$. The fine-tuned interplay within the vertex structures (2.16) led to the current equation. Whether this current-picture holds for a nonzero

ν_2 requires further investigation. If it does, it would be intriguing to explore whether there are specific values of ν_1 and ν_2 that result in the conservation of lower-spin currents, expressed as $\partial \cdot j_{s \leq 2} = 0$, while simultaneously breaking the HS currents.

VI. CONCLUDING NOTES

In this paper, we have addressed the problem of higher-spin symmetry breaking in a toy model example: the holomorphic sector of the 4D higher-spin theory, also known as self-dual or chiral. The standard higher-spin vacuum is invariant under AdS isometries and, more broadly, under global higher-spin symmetry, where the AdS algebra is a maximal finite-dimensional subalgebra. We mildly break this symmetry by modifying the vacuum, introducing a nonzero scalar expectation that is only nonzero in the AdS radial direction associated with the Poincaré coordinate z . This scalar profile represents a mixture of two conformal branches, characterized by two arbitrary parameters. For simplicity, we focus on a one-parameter vacuum where the scalar has a conformal dimension of $\Delta = 1$, setting the parameter associated with the branch $\Delta = 2$ to zero. The remaining parameter ν represents a scale of symmetry breaking in our model. The leftover symmetry is described by the Poincaré algebra in three dimensions. In other words, the symmetry of a 3D AdS slice $z = \text{const}$ is unbroken.

As a classical solution, the obtained vacuum is perfectly regular [see Eq. (4.1b)]. Its unfolded realization in the star-product algebra introduces a Fock projector that simplifies the analysis of nonlinear vertices by reducing dependence on the generating oscillators. The Fock projector results in a substantial simplification of the linearized dynamics on the symmetry-broken vacuum that requires accounting for all-order in ν contributions. As a side remark, it is of interest that Fock projectors frequently appear in higher-spin theory, from black holes [81–84] and classical solutions [75,85] to holography [77,86–90].

The analysis of the free field dynamics has been carried out using the holomorphic generating system of [54], which gives us access to all-order interacting vertices in their maximally local form [55]. Typically of the Vasiliev construction, free fields are described by 1-form gauge fields and 0-form generalized Weyl tensors. The gauge fields emerge as cohomologies of the operator that depends on the vacuum. For the standard vacuum, this operator is simply the de Rham operator d_z , while the gauge fields appear as z -independent functions. In our case with the symmetry-broken vacuum, the operator takes a ν -dependent form (4.7). Finding cohomologies of this operator is challenging. We have focused our analysis on the z -independent cohomologies, which have been successfully identified. However, since this set is not complete, consistency constraints arise that limit the 0-form module accordingly. Specifically, among the Weyl 0-forms of all

helicities, only those with helicities $s \geq -1$ are permitted by consistency, while those with $s < -1$ must be excluded.

Let us stress once again that our consideration of free field dynamics is limited to excitations with $s \geq -1$. This analysis reveals several important features:

- (i) The dependence on ν completely disappears in the gauge field sector, while only linear in ν terms contribute to the Weyl sector of 0-forms. The cancellation of higher-order in ν terms occurs due to our selection of gauge fields, the characteristics of the vacuum Fock projector, and a unique structure of the holomorphic vertices, such as a specific property of the vertex integration domains (2.19) that has not been previously recognized.
- (ii) Among the infinitely many Weyl tensors with helicities $s \geq -1$, only the case $s = -1$ sources the gauge field, implying that the higher-spin gauge sector decouples for all non-negative helicities. For $s = -1$, there is the self-dual Maxwell source.
- (iii) The Weyl sector also disentangles from the gauge fields. Its dual form corresponds to certain current equations, but unlike the standard Flato and Fronsdal case, these currents generally do not conserve. Furthermore, the nonconservation of the helicity s current involves a contribution from all the allowed helicities s' with $s' \leq s - 2$. In contrast, lower spins $s = \pm 1, \pm 1/2, 0$ exhibit different behavior: their equations are either unaffected by symmetry breaking or, as in the case of $s = 1$, the corresponding current remains conserved.

Let us discuss some aspects of the linearized analysis of the broken phase that have not been fully addressed in our investigation. First, since we do not have the complete set of cohomologies of the vacuum operator (4.7), we cannot approach fields with helicities $s < -1$. We do not anticipate these fields to decouple, nor do we expect the corresponding currents to become independent of the gauge fields. Incorporating the missing degrees of freedom from the z -dependent cohomologies introduces 0-form helicities $s < -1$. These helicities are expected to generate gauge fields, which may also be intertwined with the evolution of HS Weyl tensors. This kind of analysis is crucial for gaining a comprehensive understanding of free field dynamics around the vacuum we are considering. However, it is likely to be more complex, as we do not expect that higher-order terms in ν will be absent in this case.

Another interesting area for future research is to explore the effects of the vacuum parameter ν_2 in (3.15), which we set to zero for simplicity. We hope to report on these problems elsewhere.

ACKNOWLEDGMENTS

We would like to thank A. Korybut, N. Misuna for fruitful discussions. We also thank A. Korybut, D. Ponomarev, M. Povarnin, A. Tarusov, K. Ushakov, and

M. A. Vasiliev for their comments on the draft and valuable suggestions. We are grateful for the financial support from the Foundation for the Advancement of Theoretical Physics and Mathematics “BASIS.”

DATA AVAILABILITY

No data were created or analyzed in this study.

APPENDIX A: DERIVING VACUUM

Here we derive the vacuum solution (3.14), (3.15), which solves Eq. (2.2). For convenience, let us reproduce again the generating equations we need to solve

$$d_x W + W * W = 0, \quad (\text{A1a})$$

$$d_z W + \{W, \Lambda\}_* + d_x \Lambda = 0, \quad (\text{A1b})$$

$$d_x C + (W(z', y) *_y C - C *_y W(z', -y))|_{z'=-y} = 0, \quad (\text{A1c})$$

where

$$\Lambda = dz^\alpha z_\alpha \int_0^1 d\tau \tau C(-\tau z, \bar{y}) e^{i\tau z y}. \quad (\text{A2})$$

We start out with an ansatz that assumes the vacuum connection W is exactly the same as in the AdS space (3.9), while the field C is nonzero and contains scalar degrees of freedom only. Additionally, we assume the scalar profile is independent of the 3D coordinates $x_{a\bar{b}}$. So, we set

$$W = \Omega, \quad C = C(z, p), \quad (\text{A3})$$

where we introduce the variable $p := y\bar{y}$ and Ω is defined in (3.9). The first Eq. (A1a) is obviously satisfied. Substituting the ansatz (A3) into (A1c), we arrive at the following system:

$$\partial_z C + \frac{1}{2z} (p - 2\partial_p - p\partial_p^2) C = 0 \quad (\text{A4a})$$

$$C - 2\partial_p C + \partial_p^2 C = 0 \quad (\text{A4b})$$

which immediately gives rise to two branches (3.18)

$$C(z, p) = C_0^{\Delta=1} + C_0^{\Delta=2} := \nu_1 C_1(z, p) + \nu_2 C_2(z, p), \quad (\text{A5})$$

where we denote

$$C_1(z, p) = ze^p, \quad C_2(z, p) = z^2(p+1)e^p. \quad (\text{A6})$$

And now we need to check if (A1b) is satisfied. Note that $d_z \Omega = 0$, so Eq. (A1b) becomes

$$d_x \Lambda + \{\Omega, \Lambda\}_* = 0. \quad (\text{A7})$$

Substituting the AdS connection (3.9) into (A1b) gives us

$$\partial_z \Lambda + \frac{1}{4z} [p, \Lambda]_* = 0, \quad (\text{A8a})$$

$$dx^{\mu\nu} [y_\mu^+ y_\nu^+, \Lambda]_* = 0. \quad (\text{A8b})$$

The left-hand side of Eq. (A8a) can be calculated directly. Upon integration by parts in τ , the result takes the following form:

$$\begin{aligned} \partial_z \Lambda + \frac{1}{4z} [p, \Lambda]_* &= dz^\alpha z_\alpha \int_0^1 d\tau \tau e^{i\tau zy} \\ &\times \left[\partial_z C + \frac{1}{2z} (\bar{p} C - 2\partial_{\bar{p}} C - \bar{p} \partial_{\bar{p}}^2 C) \right], \end{aligned} \quad (\text{A9})$$

where

$$\bar{p} := -\tau z \bar{y} \quad \text{and} \quad C = C(z, \bar{p}). \quad (\text{A10})$$

Notice, the integrand contains exactly Eq. (A4a) with a redefined variable $\bar{p}$ in place of p . This means that both branches (A5) solve (A8a). Now let us take a look at (A8b). For the branch $\Delta = 1$, Λ acquires the following form:

$$\Lambda_1 \equiv \Lambda[C_1] = z dz^\alpha z_\alpha \int_0^1 d\tau \tau e^{i\tau zy^+}. \quad (\text{A11})$$

Note that Λ_1 depends on variables Y through y^+ only. Now it is easy to check that (A8b) is satisfied for C_1 corresponding to the branch $\Delta = 1$. To see this, the following commutation relations appear useful:

$$[y_\mu^+, y_\nu^+]_* = 0, \quad [z_\mu, \bullet]_* = 0. \quad (\text{A12})$$

Thus, Ω and $C_0^{\Delta=1}$ indeed solve Eq. (A1). One can do a similar computation to check that the $\Delta = 2$ branch *does not* satisfy (A8b). It is not difficult to make sure that no combination (A5) other than $\nu_2 = 0$ satisfies (A8b). More broadly, there are no solutions of (A8b) with $C = C(z, p)$ except for $C \sim C_1$. Indeed, computing the commutator, Eq. (A8b) boils down to

$$dz^\alpha L_\alpha = 0 \quad (\text{A13})$$

with

$$\begin{aligned} \frac{1}{4} L_\alpha &= dx^{\mu\nu} y_\mu z_\nu z_\alpha \left(\int_0^1 d\tau \tau^2 e^{i\tau zy} h - \int_0^1 d\tau \tau^3 e^{i\tau zy} h \right) \\ &- i dx_\alpha^\nu z_\nu \int_0^1 d\tau \tau^2 e^{i\tau zy} h \\ &+ i dx^{\mu\nu} \bar{y}_\mu z_\nu z_\alpha \left(\int_0^1 d\tau \tau^2 e^{i\tau zy} h - \int_0^1 d\tau \tau^3 e^{i\tau zy} \partial_p h \right), \end{aligned} \quad (\text{A14})$$

where

$$h \equiv \partial_p C - C. \quad (\text{A15})$$

Each contribution from (A14) has its own spinor structure, so they cannot cancel each other. Therefore we have to impose

$$\int_0^1 d\tau \tau^2 e^{i\tau zy} h = \int_0^1 d\tau \tau^3 e^{i\tau zy} h = \int_0^1 d\tau \tau^3 e^{i\tau zy} \partial_p h = 0, \quad (\text{A16})$$

that gives us as a consequence $h = 0$, or

$$\partial_p C - C = 0, \quad (\text{A17})$$

implying the only solution of (A8b) has the form

$$C(z, p) = f(z) e^p. \quad (\text{A18})$$

We see that the result is proportional to C_1 . The function $f(z)$ is determined by the vanishing of the integrand of (A9).

1. Branch $\Delta = 2$

Despite the branch $C_0^{\Delta=2}$ with $W = \Omega$ not solving (A1), it does so for the modified vacuum connection W . To see this, we modify the connection 1-form (3.9) by adding a certain correction ϖ , while leaving field C unchanged

$$W = \Omega + \nu_2 \varpi(z, Y; z),$$

$$C_0^{\Delta=2}(z, p) := \nu_2 C_2 = \nu_2 z^2 (1 + p) e^p, \quad (\text{A19})$$

where we assume ϖ to be ν_2 -independent. Substituting (A19) into (A1), we have

$$\nu_2 (d_x \varpi + \{\Omega, \varpi\}_*) + \nu_2^2 \varpi * \varpi = 0, \quad (\text{A20a})$$

$$\nu_2 (d_z \varpi + \{\Omega, \Lambda_2\}_* + d_x \Lambda_2) + \nu_2^2 \{\varpi, \Lambda_2\}_* = 0, \quad (\text{A20b})$$

$$\nu_2^2 (\varpi(z', y, \bar{y}) *_{\bar{y}} C_2 - C_2 *_{\bar{y}} \varpi(z', -y, \bar{y}))|_{z'=-y} = 0. \quad (\text{A20c})$$

As long as ν_2 is an arbitrary parameter and neither of the fields ϖ , Λ_2 , C_2 depend on ν_2 , each power of ν_2 has to vanish independently. This means the following chain of equations must hold:

$$d_x \varpi + \{\Omega, \varpi\}_* = 0, \quad (\text{A21a})$$

$$\varpi * \varpi = 0, \quad (\text{A21b})$$

$$d_z \varpi + \{\Omega, \Lambda_2\}_* + d_x \Lambda_2 = 0, \quad (\text{A21c})$$

$$\{\varpi, \Lambda_2\}_* = 0, \quad (\text{A21d})$$

$$(\varpi(z', y, \bar{y}) *_y C_2 - C_2 *_y \varpi(z', -y, \bar{y}))|_{z'=-y} = 0. \quad (\text{A21e})$$

Using the earlier results obtained in (A7)–(A9), we note that Eq. (A21c) reduces to

$$d_z \varpi = -\frac{dx^{\alpha\beta}}{8z} [y_\alpha^+ y_\beta^+, \Lambda_2]_*. \quad (\text{A22})$$

The latter equation can be solved by the standard contracting homotopy (see footnote 9) and we also make use of (A14) for the commutator on the right-hand side. Specifically, we find

$$\varpi = \frac{z^\alpha}{8z} \int_0^1 d\tau L_\alpha(\tau z, y) = \frac{iz}{2} dx^{\alpha\beta} z_\alpha z_\beta \int_0^1 d\tau \tau (1-\tau) e^{i\tau z y^+}. \quad (\text{A23})$$

Now we need to check if the obtained deformation ϖ satisfies the whole chain of Eq. (A21). The following calculation allows us to see that this is indeed the case. First off

$$z_\alpha z_\beta e^{itz y^+} * z_\mu z_\nu e^{i\tau z y^+} = \frac{(1-t)^2(1-\tau)^2}{(1-\tau t)^6} z_\mu z_\nu z_\alpha z_\beta \times \exp \left[iz y^+ \frac{t + \tau - 2\tau t}{1 - \tau t} \right], \quad (\text{A24})$$

which immediately proves (A21b) because

$$\varpi * \varpi \sim dx^{\alpha\beta} \wedge dx^{\mu\nu} z_\alpha z_\beta z_\mu z_\nu = 0. \quad (\text{A25})$$

The analysis of (A21d), (A21e) reveals similar to (A24) star products, as we find that both equations are indeed satisfied. That the first Eq. (A21a) is satisfied can be observed from comparing ϖ and $\Lambda_0 = \nu_1 \Lambda_1$ from (4.1c),

$$\varpi = \frac{iz}{2} dx^{\alpha\beta} \int_0^1 d\tau (1-\tau) \tau z_\alpha z_\beta e^{i\tau z y^+} \quad \text{vs} \quad \Lambda_1 = z dz^\alpha \int_0^1 d\tau \tau z_\alpha e^{i\tau z y^+}. \quad (\text{A26})$$

It is important that both ϖ and Λ_1 have the same dependence on z . It can be seen that Eqs. (A21a) and (A7) are essentially the same equations; see also the results of the previous subsection. Namely, it is easy to see that both Eq. (A8a) and Eq. (A8b) are satisfied for ϖ for the same reasons as for Λ_1 . This means that the whole chain of equations (A21) is satisfied. Eventually, we see that the fields $W = \Omega + \nu_2 \varpi$ and $C = \nu_2 C_2$ form a solution. Now that it is shown that the two branches satisfy equations of motion separately, a question arises whether an arbitrary mixture of these with coefficients ν_1 and ν_2 is still a vacuum? This would be the case provided

$$[\varpi, \Lambda_1]_* = 0, \quad (\text{A27})$$

which is straightforward to verify. Therefore, (3.14) and (3.15) solve (2.2).

APPENDIX B: VERTEX INTEGRATION DOMAINS

Here we provide a proof of the important property of the integration domains

$$\bigsqcup_{k-\text{odd}} \mathcal{D}_n^{[k]} = \bigsqcup_{k-\text{even}} \mathcal{D}_n^{[k]}, \quad (\text{B1})$$

where the domains $\mathcal{D}_n^{[k]}$ appear in the construction of the higher-spin interaction vertices (2.16). These are defined by a set of inequalities

$$\mathcal{D}_n^{[k]} = \begin{cases} \eta_1 + \dots + \eta_n = 1, & \eta_i \geq 0, \\ \xi_1 + \dots + \xi_n = 1, & \xi_i \geq 0, \\ C_i \leq 0, & i \in [1, k-1], \\ C_i \geq 0, & i \in [k+1, n-1]. \end{cases}, \quad C_i \equiv \eta_i \xi_{i+1} - \eta_{i+1} \xi_i \quad (\text{B2})$$

or in a short form as follows

$$\mathcal{D}_n^{[k]} = \{C_1 \leq 0, \dots, C_{k-1} \leq 0 | C_{k+1} \geq 0, \dots, C_n \geq 0\}. \quad (\text{B3})$$

Let us introduce a set of auxiliary domains

$$\Delta_n^{[k]} \equiv \{C_1 \leq 0, \dots, C_{k-1} \leq 0 | C_k \geq 0, \dots, C_n \geq 0\}, \quad \Delta_n^{[1]} \equiv \mathcal{D}_n^{[0]}, \quad \Delta_n^{[n]} \equiv \mathcal{D}_n^{[n]}. \quad (\text{B4})$$

Here all the assumptions for ξ, η are the same as for $\mathcal{D}_n^{[k]}$. Using these domains, we can rewrite $\mathcal{D}$ as

$$\mathcal{D}_n^{[k]} = \Delta_n^{[k]} \cup \Delta_n^{[k+1]}. \quad (\text{B5})$$

Intersection $\Delta_n^{[k]} \cap \Delta_n^{[k+1]}$ is not empty but a set of zero measure

$$\Delta_n^{[k]} \cap \Delta_n^{[k+1]} = \{C_1 \leq 0, \dots, C_{k-1} \leq 0 | C_k = 0 | C_{k+1} \geq 0, \dots, C_n \geq 0\} \quad (\text{B6})$$

Recall that we are dealing with integration domains, so this intersection can be freely omitted. To emphasize this we use $\sqcup$ as union up to a set of measure zero. Now one easily obtains the property (B1)

$$\bigsqcup_{k-\text{odd}} \mathcal{D}_n^{[k]} = \Delta_n^{[1]} \sqcup \Delta_n^{[2]} \sqcup \dots \sqcup \Delta_n^{[n-1]} \sqcup \Delta_n^{[n]} = \bigsqcup_{k-\text{even}} \mathcal{D}_n^{[k]}. \quad (\text{B7})$$

APPENDIX C: VERTICES $\Upsilon(\mathbf{w}(y^+), C_0^n)$

Let us show that the vertices $\Upsilon(\mathbf{w}(y^+), C_0^n)$, while emerging in the linearization around (4.1), appear to be zero for any n . To this end, we rewrite vertex (2.16) in the differential (Taylor) form using the notation from [50,55] as

$$\begin{aligned} \Upsilon(\omega, C^n) &= \sum_{k=0}^n \Phi_n^k(y|t; p) \left(\prod_{i=1}^k \star C_0(y_i, \bar{y}) \right) \\ &\quad \star \omega(y_t, \bar{y}) \star \left(\prod_{i=k+1}^n \star C_0(y_i, \bar{y}) \right) \Big|_{y_i=y_t=0}, \quad (\text{C1}) \end{aligned}$$

where

$$\Phi_n^k(y|t; p) = (-)^{k+1} (ty)^{n-1} \int_{\mathcal{D}_n^{[k]}} e^{-iyP_n(\xi) - itP_n(\eta) + ityS_n^k} \quad (\text{C2})$$

contains the following differential operators

$$t_\mu = -i \frac{\partial}{\partial y_t^\mu}, \quad p_{i\mu} = -i \frac{\partial}{\partial y_i^\mu} \quad (\text{C3})$$

with

$$S_n^{[k]} = - \sum_{s=1}^k \xi_s + \sum_{s=k+1}^n \xi_s + \sum_{i < j} (\xi_i \eta_j - \xi_j \eta_i), \quad (\text{C4})$$

$$\begin{aligned} \Upsilon(\omega, C_0^n) &= \sum_{k=0}^n (-)^{k+1} (ty)^{n-1} \int_{\mathcal{D}_n^{[k]}} \exp \left[(y+t)\bar{y} + i(ty) \left(1 - 2 \sum_1^k \xi_s \right) \right] \omega \left[y_t, \bar{y} + iy \left(1 - 2 \sum_1^k \xi_s \right) + it \left(1 - 2 \sum_1^k \eta_s \right) \right] \Big|_{y_t=0}. \end{aligned} \quad (\text{C10})$$

Now we substitute $\omega(y, \bar{y}) = \mathbf{w}(y + i\bar{y})$ to arrive at

$$\Upsilon(\mathbf{w}, C_0^n) = e^{y\bar{y}} \sum_{k=0}^n (-)^{k+1} (ty)^{n-1} \int_{\mathcal{D}_n^{[k]}} \mathbf{w} \left[y_t - t \left(1 - 2 \sum_1^k \eta_s \right) \right] \Big|_{y_t=0}. \quad (\text{C11})$$

As a final step, in order to act with operator t on y_t from the left, we use the decomposition

$$\mathbf{w}(y' - At) = \int d^2 u d^2 v e^{iu(v+At)} \mathbf{w}(y' + v), \quad (\text{C12})$$

and

$$P_n(a) = \sum_{i=0}^n p_i a_i. \quad (\text{C5})$$

We need now to calculate $\star$ products of C_0 . Additionally, we set $\nu = 1$ for convenience, since its particular value is not important for the following analysis. For the product of two C_0 's one easily obtains

$$\begin{aligned} C_0(y_1, \bar{y}) \star C_0(y_2, \bar{y}) &= z^2 e^{y_1 \bar{y}} \star e^{y_2 \bar{y}} \\ &= z^2 e^{(y_1+y_2)\bar{y} + iy_1 y_2}. \end{aligned} \quad (\text{C6})$$

Therefore,

$$\prod_{i=1}^k \star C_0(y_i, \bar{y}) = z^k \exp \left[\sum_{s=1}^k y_s \bar{y} + i \sum_{1 \leq i < j \leq k} y_i y_j \right]. \quad (\text{C7})$$

Similarly,

$$\begin{aligned} &\left(\prod_{i=1}^k \star C_0(y_i, \bar{y}) \right) \star \omega(y', \bar{y}) \star \left(\prod_{i=k+1}^n \star C_0(y_i, \bar{y}) \right) \\ &= z^n \exp \left[\sum_{s=1}^n y_s \bar{y} + i \sum_{1 \leq i < j \leq n} y_i y_j \right] \\ &\quad \times \omega \left(y', \bar{y} - i \sum_{s=1}^k y_s + i \sum_{s=k+1}^n y_s \right). \end{aligned} \quad (\text{C8})$$

Substituting this into (C1) and using that

$$\sum_{i=1}^n \xi_i = \sum_{i=1}^n \eta_i = 1 \quad (\text{C9})$$

gives us

which upon action of the translation operator generated by the exponential of t takes us to the following result:

$$\Upsilon(\mathbf{w}(y^+), C_0^n) = e^{y\bar{y}}(ty)^{n-1} \sum_{k=0}^n (-)^{k+1} \int_{\mathcal{D}_n^{[k]}} \mathbf{w}(y_t)|_{y_t=0}. \quad (\text{C13})$$

The latter expression is just zero as a consequence of (2.19), thus,

$$\Upsilon(\mathbf{w}(y^+), C_0^n) = 0. \quad (\text{C14})$$

APPENDIX D: CONSISTENCY

Here we check consistency of the linearized equations (5.10a), (5.10b), which we can write down as

$$\partial_z T = \frac{1}{2}(\partial\bar{\partial}T + \nu w\bar{\partial}J[T]), \quad (\text{D1a})$$

$$d_x T = \frac{i}{2}dx^{\alpha\beta}(\partial_\alpha\bar{\partial}_\beta T + \nu w_\alpha\bar{\partial}_\beta J[T]), \quad (\text{D1b})$$

Specifically, the following two integrability conditions should be satisfied:

$$d_x^2 T = 0, \quad [d_x, \partial_z]T = 0. \quad (\text{D2})$$

Let us introduce also the following shorthand notation:

$$T^- = T(\tau w, \bar{w} - i[1 - \tau]w), \quad T^+ = T(\tau w, \bar{w} + i[1 - \tau]w), \quad (\text{D3})$$

$$J[T] = \int_0^1 d\tau(1 - \tau)(T^- - T^+), \quad (\text{D4})$$

$$H_{\mu\nu}[T] = \frac{1}{4}(\partial_\mu\bar{\partial}_\nu T + \partial_\nu\bar{\partial}_\mu T + \nu w_\mu\bar{\partial}_\nu J[T] + \nu w_\nu\bar{\partial}_\mu J[T]), \quad (\text{D5})$$

where we recall that spinorial ∂ and $\bar{\partial}$ denote differentiation with respect to the full arguments of $T(s, \bar{s})$. When necessary, we distinguish differentiation with respect to a particular variable by marking

$$w' = w'' = \tau w, \quad \bar{w}' = \bar{w} - i(1 - \tau)w, \\ \bar{w}'' = \bar{w} + i(1 - \tau)w, \quad (\text{D6})$$

which brings in our calculations differentiations of the form

$$\partial' = \frac{\partial}{\tau} + i\frac{1 - \tau}{\tau}\bar{\partial}, \quad \partial'' = \frac{\partial}{\tau} - i\frac{1 - \tau}{\tau}\bar{\partial}. \quad (\text{D7})$$

Let us start with checking the consistency of (D1b).

(i) Equation (D1b) is rewritten as

$$d_x T = id_x^{\mu\nu} H_{\mu\nu}[T], \quad (\text{D8})$$

while its consistency condition is

$$0 = id_x^{\alpha\beta} \wedge dx^{\mu\nu} \partial_{\alpha\beta} H_{\mu\nu}[T]. \quad (\text{D9})$$

The ν -independent contribution cancels out due to consistency of the $\nu = 0$ case. We are left with the following:

$$4dx^{\alpha\beta} \wedge dx^{\mu\nu} \partial_{\alpha\beta} H_{\mu\nu}[T] \\ = i\nu dx^{\alpha\beta} \wedge dx^{\mu\nu} \bar{\partial}_\nu \bar{\partial}_\beta (w_\alpha \partial_\mu + \epsilon_{\mu\alpha}) J[T] \\ + 2\nu dx^{\alpha\beta} \wedge dx^{\mu\nu} w_\mu \bar{\partial}_\nu \int_0^1 d\tau(1 - \tau) \partial_{\alpha\beta} (T^- - T^+). \quad (\text{D10})$$

The integrand is further transformed using (D6), (D7)

$$\partial_{\alpha\beta} T^- = \frac{i}{4}(\partial'_\alpha \bar{\partial}'_\beta + \partial'_\beta \bar{\partial}'_\alpha) T(w', \bar{w}') \\ + \frac{i\nu}{4} w'_\alpha \bar{\partial}'_\beta J[T(w', \bar{w}')] \\ = \frac{i}{4\tau}(\partial_\alpha \bar{\partial}_\beta + \partial_\beta \bar{\partial}_\alpha) T^- + i\frac{1 - \tau}{2\tau} \bar{\partial}_\alpha \bar{\partial}_\beta T^- \\ + \frac{i\nu\tau}{4} (w_\alpha \bar{\partial}_\beta + w_\beta \bar{\partial}_\alpha) J[T^-]. \quad (\text{D11})$$

The last term above brings the ν^2 terms, which cancel independently

$$\nu^2 \cdot dx^{\alpha\beta} \wedge dx^{\mu\nu} w_\mu \bar{\partial}_\nu w_\alpha \bar{\partial}_\beta \int_0^1 d\tau(1 - \tau) \tau J[T^-] = 0 \quad (\text{D12})$$

and analogously with T^+ . So, one is only left to check the terms proportional to ν

$$-\frac{4i}{\nu} dx^{\alpha\beta} \wedge dx^{\mu\nu} \partial_{\alpha\beta} H_{\mu\nu} = dx^{\alpha\beta} \wedge dx^{\mu\nu} \bar{\partial}_\nu \bar{\partial}_\beta (w_\alpha \partial_\mu + \epsilon_{\mu\alpha}) J[T] + dx^{\alpha\beta} \wedge dx^{\mu\nu} \bar{\partial}_\nu \bar{\partial}_\beta \int_0^1 d\tau(1 - \tau) \left[\frac{1}{\tau} w_\mu \partial_\alpha T^- + i\frac{1 - \tau}{\tau} w_\mu \bar{\partial}_\alpha T^- \right] \\ - dx^{\alpha\beta} \wedge dx^{\mu\nu} \bar{\partial}_\nu \bar{\partial}_\beta \int_0^1 d\tau(1 - \tau) \left[\frac{1}{\tau} w_\mu \partial_\alpha T^+ - i\frac{1 - \tau}{\tau} w_\mu \bar{\partial}_\alpha T^+ \right]. \quad (\text{D13})$$

Now we use the antisymmetrization rule for two-component spinors

$$2dx^{\alpha\beta} \wedge dx^{\mu\nu} \bar{\partial}_\nu \bar{\partial}_\beta = \epsilon^{\alpha\mu} \cdot dx_\rho^\beta \wedge dx^{\rho\nu} \bar{\partial}_\nu \bar{\partial}_\beta \quad (D14)$$

and the integration by parts using

$$\begin{aligned} \frac{\partial}{\partial \tau} T^- &= w^\mu (\partial'_\mu + i\bar{\partial}'_\mu) T^- = \frac{w^\mu (\partial + i\bar{\partial})_\mu}{\tau} T^-, \\ \frac{\partial}{\partial \tau} T^+ &= w^\mu (\partial'_\mu - i\bar{\partial}'_\mu) T^+ = \frac{w^\mu (\partial - i\bar{\partial})_\mu}{\tau} T^+. \end{aligned} \quad (D15)$$

The result is

$$\epsilon_{\alpha\mu} dx^{\alpha\beta} \wedge dx^{\mu\nu} \bar{\partial}_\nu \bar{\partial}_\beta [T(0; \bar{w} + iw) - T(0; \bar{w} - iw)] = 0. \quad (D16)$$

Which is satisfied by the following general T -module

$$T(0, \bar{w}) = T_0 + T_\alpha \bar{w}^\alpha + \frac{1}{2} T_{\alpha\beta} \bar{w}^\alpha \bar{w}^\beta. \quad (D17)$$

- (ii) Now we need to check the condition $[d_x, \partial_z]T = 0$. The corresponding equation splits into three with respect to power of ν . Again, the ν -independent part vanishes automatically and we are left with the following:

$$\begin{aligned} \nu: dx^{\alpha\beta} (\partial_\alpha \bar{\partial}_\beta w \bar{\partial} J[T] - \partial \bar{\partial} w_\alpha \bar{\partial}_\beta J[T]) \\ + dx^{\alpha\beta} w_\alpha \bar{\partial}_\beta \int_0^1 d\tau (1-\tau) [\partial' \bar{\partial} T^- - \partial'' \bar{\partial} T^+] \\ - dx^{\alpha\beta} w \bar{\partial} \int_0^1 d\tau (1-\tau) [\partial'_\alpha \bar{\partial}_\beta T^- - \partial''_\alpha \bar{\partial}_\beta T^+] = 0, \end{aligned} \quad (D18)$$

$$\begin{aligned} \nu^2: dx^{\alpha\beta} w_\alpha \bar{\partial}_\beta \int_0^1 d\tau (1-\tau) (w' \bar{\partial} J[T^-] - w'' \bar{\partial} J[T^+]) \\ - dx^{\alpha\beta} w \bar{\partial} \int_0^1 d\tau (1-\tau) (w'_\alpha \bar{\partial}_\beta J[T^-] - w''_\alpha \bar{\partial}_\beta J[T^+]) = 0. \end{aligned} \quad (D19)$$

Recalling that $w' = w'' = \tau w$, one can see that Eq. (D19) is satisfied. To check the first equation (D18) one need to use the following useful feature of two-dimensional spinors

$$\begin{aligned} w \bar{\partial} \partial_\alpha \bar{\partial}_\beta - w_\alpha \bar{\partial}_\beta \partial \bar{\partial} &= \bar{\partial}_\beta \bar{\partial}^\gamma (w_\gamma \partial_\alpha - w_\alpha \partial_\gamma) \\ &= \epsilon_{\gamma\alpha} \cdot \bar{\partial}_\beta \bar{\partial}^\gamma w \partial. \end{aligned} \quad (D20)$$

Using this expression and integrating by parts (D18) one arrives at the same result

$$\bar{\partial}_\alpha \bar{\partial}_\beta [T(0; \bar{w} + iw) - T(0; \bar{w} - iw)] = 0. \quad (D21)$$

Constraint (D17) should commute with d_x and d_z , thus leading to a set of additional constraints. These turn out to be the following:

$$T_{\alpha(m), \beta(n)} = 0 \quad \text{for } n - m > 2. \quad (D22)$$

To prove this, consider our Eqs. (5.10), (5.10b), which we combine in a single one [recall $x = (x, z)$]

$$d_x T_{\alpha(m), \beta(n)} = -i z e^{\gamma\rho} \left(T_{\gamma\alpha(m), \rho\beta(n)} + 4i\nu \epsilon_{\alpha\gamma} \sum_{k=1}^{\lfloor \frac{m}{2} \rfloor} \frac{k(-)^k}{m+1} T_{\alpha(m-2k), \alpha(2k-1)\beta(n)\rho} \right) \quad (D23)$$

using the vierbein (3.5c). The consistency condition (D17) reads

$$\bar{J}_{\beta(n)} := T_{\alpha(0), \beta(n)} = 0, \quad n > 2 \quad (D24)$$

For the cases where $m = 0, 1$, the sum on the right of (D23) does not contribute. We have

$$d_x \bar{J}_{\beta(n)} = -i z e^{\gamma\rho} T_{\gamma, \rho\beta(n)}, \quad (D25a)$$

$$d_x T_{\alpha, \beta(n)} = -i z e^{\gamma\rho} T_{\gamma\alpha, \rho\beta(n)}. \quad (D25b)$$

Combining together (D24), (D25a), and (D25b), we conclude that

$$T_{\alpha, \beta(n+1)} = 0, \quad T_{\alpha(2), \beta(n+2)} = 0 \quad \text{for all } n > 2. \quad (D26)$$

Notice that the above equations hold true because the vierbein contains both symmetric and antisymmetric parts of spinorial indices. Now we return to the general equation (D23) and rewrite it as follows:

$$\begin{aligned}
i\mathbf{z}e^{\gamma\rho}T_{\gamma\alpha(m),\rho\beta(n)} &= -\mathbf{d}_x T_{\alpha(m),\beta(n)} \\
&+ 4\mathbf{z}e^{\gamma\rho}\nu\epsilon_{\alpha\gamma}\sum_{k=1}^{\lfloor\frac{m}{2}\rfloor}\frac{k(-)^k}{m+1}T_{\alpha(m-2k),\alpha(2k-1)\beta(n)\rho}.
\end{aligned}
\tag{D27}$$

We now look at the $n - m > 2$ case. Suppose we have already proven that

$$T_{\alpha(m),\beta(n>m+2)} = 0 \quad \text{for all } m, m-1, m-2, \dots, 0 \tag{D28}$$

For any m and n the sum consists of components $T_{\alpha(m-2k),\alpha(2k-1)\beta(n)\rho}$ whose difference of number of indices is $n - m + 4k > n - m > 2$. This means that for any k this component is covered by the assumption (D28). We conclude then

$$\begin{aligned}
e^{\gamma\rho}T_{\gamma\alpha(m),\rho\beta(n)} &= 0 \Rightarrow T_{\alpha(m+1),\beta(n+1)} \\
&= 0 \quad \text{for all } n - m > 2,
\end{aligned}
\tag{D29}$$

thus completing the proof.

APPENDIX E: A REMARK ON STAR-PERIODIC FUNCTIONS

This Appendix is aimed at demonstrating that functions of the form

$$\exp_* \tau D := \sum_{n=0}^{\infty} \frac{\tau^n}{n!} \underbrace{D * \dots * D}_n, \tag{E1}$$

where the dilatation operator D is defined in (3.11d), may not have well-defined symbols for certain values of τ . In particular, this is the case for periodic functions with $\tau = 2\pi in$, where n is an integer.

Suppose τ is an arbitrary number and let us look for a symbol of the exponential (E1) in the following form:

$$\exp_* \tau D = h(\tau) \exp(q(\tau)D), \tag{E2}$$

where $h(\tau)$ and $q(\tau)$ are yet to be determined. Star multiplying (E1) with D we have, on the one hand,

$$\begin{aligned}
D * \exp_* \tau D &= \frac{\partial}{\partial \tau} \exp_* \tau D \\
&= (h'(\tau) + h(\tau)q'(\tau)D) \exp(q(\tau)D),
\end{aligned}
\tag{E3}$$

where $f'(\tau)$ denotes derivative with respect to the variable τ . On the other hand, using (2.8) one finds that

$$D * = -\frac{1}{4}(y + i\partial)_\alpha(\bar{y} + i\bar{\partial})^\alpha, \tag{E4}$$

from which it is straightforward to obtain

$$\begin{aligned}
D * \exp_* \tau D &:= D * (h \exp q D) \\
&= \left(D - \frac{1}{8}q - \frac{1}{16}q^2 D \right) h \exp q D.
\end{aligned}
\tag{E5}$$

Equating the right-hand sides of (E3) and (E5) to each other gives us the following differential equations on functions h and q :

$$h' = -\frac{1}{8}h \cdot q, \tag{E6}$$

$$q' = 1 - \left(\frac{q}{4}\right)^2. \tag{E7}$$

For $\tau = 0$, in addition, we have $\exp_*(0) = 1$. This brings us to the solution of the form

$$q(\tau) = 4 \tanh \frac{\tau}{4}, \quad h(\tau) = \frac{1}{\cosh^2 \frac{\tau}{4}} \tag{E8}$$

Therefore, for the symbol of the star-exponential, we have

$$\exp_*(\tau D) = \frac{1}{\cosh^2 \frac{\tau}{4}} \exp\left(4D \tanh \frac{\tau}{4}\right), \tag{E9}$$

or changing parametrization by introducing $s := e^{\tau/2}$,

$$\exp_*(D \log s^2) = \frac{4s}{(s+1)^2} \exp 4\left(\frac{s-1}{s+1}\right)D. \tag{E10}$$

Notably, for $\tau = 2\pi in$ from (E9) it follows that

$$\exp_*(2\pi in D) = \begin{cases} 1, & n - \text{even} \\ \infty, & n - \text{odd} \end{cases} \tag{E11}$$

$n \in \mathbb{Z}$ is exactly the case that has emerged in the process of analyzing periodic degrees of freedom in Sec. IV. This result indicates that for special values of n , such as in (E11), the star exponential (E1) is not analytic in D . Perhaps it makes sense to consider it as a distribution.

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