

On Projective Hoops: Loops in Hyperspace

Dharmesh Jain* and Warren Siegel†

C. N. Yang Institute for Theoretical Physics, State University of New York, Stony Brook, New York, 11794-3840, USA

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We (re)derive the propagators and Feynman rules for the massless scalar and vector multiplets in $N = 2$ projective superspace (“projective hyperspace”). With these, we are able to calculate both the divergent and finite parts of 2, 3, & 4-point functions at 1-loop for $N = 2$ super-Yang-Mills theory, explicitly in projective hyperspace itself. We find that effectively only the coupling constant needs to be renormalized, unlike in the $N = 1$ case where an independent wavefunction renormalization is also required. This feature is similar to that of the background field gauge, even though we are using ordinary Fermi-Feynman gauge. The computation of 1-hoop beta-function is then straightforward and matches with the known result. We also show that it receives no 2-hoops contributions. All these calculations provide an alternative proof of the finiteness of $N = 4$ super-Yang-Mills.

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I. INTRODUCTION

There has been a renewed interest in $N = 4$ super Yang-Mills theory (SYM) and its on-shell perturbative structure. These calculations mostly use components and/or some on-shell formulation of $N = 4$ supersymmetry, but often rely on unproven assumptions. It would be best to have an off-shell formalism for $N = 4$ supersymmetry itself, but it has been elusive for decades. The next best thing would be to use $N = 2$ off-shell formalism which, as we show in this paper, is simpler than the well-known $N = 1$ formalism.

Recently, we proposed the non-Abelian SYM action in $N = 2$ projective superspace (hyperspace) in [1]. $N = 2$ supermultiplets (hypermultiplets) in projective hyperspace have been long known since the work of Lindström and Roček [2]. The Feynman rules were derived for scalar and vector hypermultiplets in three successive papers by Gonzalez-Rey, *et al.* [3]. Some one-loop calculations involving scalar hypermultiplet’s contributions to effective action were done in [4], but as the non-Abelian action was lacking, not much could be accomplished as far as calculations involving vector hypermultiplet were concerned.

An analogous (but slightly better) situation exists in the case of harmonic hyperspace developed by GIKOS [5]. One-loop two-point functions for SYM effective action and four-point functions (both divergent & finite) with external scalar hypermultiplets were computed by them in [6]. The n -point calculations were accomplished by Buchbinder, *et al.* [7], but these are contributions to the effective action for the Abelian case only. Even a direct computation of the β -function for $N = 2$ SYM has not been done, which requires a 3-point calculation with ordinary Feynman rules. However, a 3-point calculation is unnecessary in the case of background field formalism,

which does exist for harmonic hyperspace [8]. Using this formalism, even a 4-point S -matrix calculation in $N = 4$ SYM has been done in [9], which also includes effective potential calculations similar to those in [4].

In this paper, we extend the possible set of loop calculations in projective hyperspace and show that the hypergraphs are easier to handle than their $N = 1$ counterparts. We calculate both the divergent and finite parts of 1-hoop 2, 3, & 4-point functions. It turns out that the scalar hypermultiplet action (including its coupling to vector hypermultiplet) is not renormalized at any loop order. We also find that the divergent (and some finite) 1-loop corrections to SYM effective action have the same form as the classical action (modulo their momentum dependence), proving its renormalizability.

Both the wavefunction and coupling constant are linearly renormalized at 1-loop for $N = 2$ SYM, which is not the case when $N = 1$ supergraph methods are used [10,11]. An independent (nonlinear) wavefunction renormalization is required in that case to keep the effective action renormalizable. Additionally, we learn from using hypergraph rules that there is effectively only one renormalization factor as is encountered when using background field formalism.

These 1-hoop calculations enable us to compute the well-known β -function for $N = 2$ SYM coupled to scalar hypermultiplet (matter) in any representation of the gauge group. We also perform a few “selected” 2-hoops calculations to prove its two-loop finiteness. All these calculations and a few “miraculous” cancellations also show that the β -function of $N = 4$ SYM vanishes at 1 & 2-loop(s).¹

¹Using $N = 1$ supergraph methods, finiteness of $N = 4$ SYM has been shown till 3-loops explicitly in [12,13]. Using $N = 2$ superfields and background field formalism, such cancellations leading to UV finiteness of $N = 2$ & 4 theories were explained in [14] for all loop orders.

*djain@insti.physics.sunysb.edu
†siegel@insti.physics.sunysb.edu
<http://insti.physics.sunysb.edu/~siegel/plan.html>

In the next section, we review the basics of projective hyperspace. After that, we write various hypermultiplet actions to derive the propagators and vertices, which enable us to present the revised “complete” Feynman rules to evaluate any possible hypergraph. Then, as mentioned above, we present some examples of 1 & 2-hoop(s) hypergraph calculations and the resulting consequences for $N = 2$ & 4 theories.

II. GENERIC THEORY

We review the (relevant) generalities of Projective Hyperspace that are discussed in gory details in [15].

A. Hyperspace

We start with $SU(2, 2|2)$ group element $g_{\mathcal{M}}^{\mathcal{A}}$. The $SU(2)$ bosonic (Latin) and $SU(2, 2)$ fermionic (Greek) indices contained in the group indices are divided into two parts and shuffled such that $\mathcal{M} = \{M, M'\} = \{(m, \mu), (m', \dot{\mu})\}$ with their values being $\{1, (1, 2), 1', (\dot{1}, \dot{2})\}$. Since the bosonic indices take only one value, they will be suppressed.

The projective coordinates $(4x's, 4\theta's \& 1y)$ are arranged in an off-diagonal square matrix $w_M^{A'}$ inside $g_{\mathcal{M}}^{\mathcal{A}}$. The rest of the fermionic coordinates $(\vartheta_\mu, \vartheta^{\dot{\alpha}})$ are contained in the diagonal parts of g and can be understood by the method of projection given below:

$$g: g_{\mathcal{M}}^{\mathcal{A}} \rightarrow \bar{z}_{\mathcal{M}}^{A'} \quad (2.1)$$

$$g^{-1}: g_{\mathcal{A}}^{\mathcal{M}} \rightarrow z_A^{\mathcal{M}} \quad (2.2)$$

$$\text{Constraint: } z_A^{\mathcal{M}} \bar{z}_{\mathcal{M}}^{A'} = 0 \quad (2.3)$$

$$\text{Solution: } \begin{cases} \bar{z}_{\mathcal{M}}^{A'} = (w_M^{N'}, \delta_{M'}^{N'}) \bar{u}_{N'}^{A'}; \\ z_A^{\mathcal{M}} = u_A^N (\delta_N^M, -w_N^{M'}). \end{cases} \quad (2.4)$$

The coordinates in w , u , & $\bar{u}$ are arranged as follows:

$$w_M^{A'} = \begin{pmatrix} y & \bar{\theta}^{\dot{\alpha}} \\ \theta_\mu & x_{\mu}^{\dot{\alpha}} \end{pmatrix} \quad (2.5)$$

$$u_M^A = \begin{pmatrix} I & 0 \\ \vartheta_\mu & I \end{pmatrix} \quad (2.6)$$

$$\bar{u}_{M'}^{A'} = \begin{pmatrix} I & -\bar{\vartheta}^{\dot{\alpha}} \\ 0 & I \end{pmatrix} \quad (2.7)$$

These matrices have the following finite superconformal transformations (indices are suppressed in matrix notation below):

TABLE I. Covariant Derivatives.

D 's	Projective ($\check{\Pi}$)	Reflective ($\mathcal{R}$)
d_x	∂_x	∂_x
d_θ	$\partial_\theta - \bar{\vartheta} \partial_x$	∂_θ
$\bar{d}_\theta$	$\partial_{\bar{\theta}} + \partial_x \vartheta$	$\partial_{\bar{\theta}}$
d_y	$\partial_y - \bar{\vartheta} \partial_{\bar{\theta}} - \vartheta \partial_\theta - \bar{\vartheta} \partial_x \vartheta$	∂_y
d_ϑ	∂_ϑ	$\partial_\vartheta + y \partial_\theta + \bar{\theta} \partial_x$
$\bar{d}_\vartheta$	$\partial_{\bar{\vartheta}}$	$\partial_{\bar{\vartheta}} + y \partial_{\bar{\theta}} + \partial_x \theta$

$$\bar{z}' = g_0 \bar{z},$$

$$z' = z g_0^{-1};$$

$$g_0 = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad (2.8)$$

$$g_0^{-1} = \begin{pmatrix} \tilde{d} & -\tilde{b} \\ -\tilde{c} & \tilde{a} \end{pmatrix}$$

$$\Rightarrow w' = (aw + b)(cw + d)^{-1},$$

$$u' = (w\tilde{c} + \tilde{d})^{-1}u, \quad (2.9)$$

$$\bar{u}' = \bar{u}(cw + d)^{-1}.$$

We can also construct symmetry invariants as differentials or finite differences:

$$z_A^{\mathcal{M}} d\bar{z}_{\mathcal{M}}^{A'} = u_A^M (dw_M^{M'}) \bar{u}_{M'}^{A'}, \quad (2.10)$$

$$z_{2A}^{\mathcal{M}} \bar{z}_{1\mathcal{M}}^{A'} = u_{2A}^M (w_1 - w_2)_M^{M'} \bar{u}_{1M'}^{A'}.$$

B. Covariant derivatives

It is easier to derive the symmetry generators ($G = g\partial_g$) and covariant derivatives ($D = \partial_g g$) from the infinitesimal forms of the transformations given above and in matrix form, they read:

$$G_w = \partial_w, \quad G_u = w\partial_w + u\partial_u, \quad G_{\bar{u}} = \partial_w w + \partial_{\bar{u}} \bar{u} \quad (2.11)$$

$$D_w = \bar{u}\partial_w u, \quad D_u = \partial_u u, \quad D_{\bar{u}} = \bar{u}\partial_{\bar{u}}. \quad (2.12)$$

This defines the “projective representation”, which is not quite useful for the construction of a “simple” $N = 2$ SYM action. For that, we need what is called a “reflective representation” in which the D 's are “switched” with G 's. The explicit forms of covariant derivatives for all the coordinates in both representations are given in Table I.

All the D -commutators can be read directly from Table I and are same in both the representations except the first one below, which is nontrivial only in $\mathcal{R}$:

$$\{d_{1\vartheta}, \bar{d}_{2\vartheta}\} = y_{12} d_x \quad (2.13)$$

$$\{d_{1\theta}, \bar{d}_{2\vartheta}\} = d_x = \{\bar{d}_{1\theta}, d_{2\vartheta}\} \quad (2.14)$$

$$[d_y, d_\vartheta] = d_\theta \quad \& \quad [d_y, \bar{d}_\vartheta] = \bar{d}_\theta. \quad (2.15)$$

The subscript ‘ a ’ in $d_{a\vartheta}$ ’s labels different y ’s (to condense notation, it will also label ϑ ’s wherever required), $y_{12} \equiv y_1 - y_2$ and $d_\theta \equiv d_{a\theta}$. All these commutations lead to the following useful identities:²:

$$d_{1\vartheta} d_{2\vartheta}^4 = y_{12} d_{1\theta} d_{2\vartheta}^4 \quad (2.16)$$

$$d_{1\vartheta}^4 d_{2\vartheta}^4 = y_{12}^2 \left[\frac{1}{2} \square + y_{12} d_{1\theta} d_{2\vartheta} + y_{12}^2 d_{1\theta}^4 \right] d_{2\vartheta}^4 \quad (2.17)$$

$$\delta^8(\theta_{12}) d_{1\vartheta}^4 d_{2\vartheta}^4 \delta^8(\theta_{21}) = y_{12}^4 \delta^8(\theta_{12}) \quad (2.18)$$

$$d_\vartheta^4 d_y^2 d_\vartheta^4 = \square d_\vartheta^4. \quad (2.19)$$

C. Hyperfields

We define a projective hyperfield Φ such that $d_\vartheta \Phi = \bar{d}_\vartheta \Phi = 0$. In $\tilde{\Pi}$, it just means that $\Phi \equiv \Phi(x, \theta, \bar{\theta}, y)$. This representation is useful for defining actions in projective hyperspace. In $\mathcal{R}$, the dependence on $(\vartheta \& \bar{\vartheta})$ is nontrivial and looks like: $\Phi \equiv \Phi(x + \vartheta \bar{\theta} + \theta \bar{\vartheta} - y \vartheta \bar{\vartheta}, \theta - y \vartheta, \bar{\theta} - y \bar{\vartheta}, y)$. This representation is more suited for writing actions in the “full” hyperspace with 8 θ ’s.

The superconformal transformation of Φ with a (super-scale) weight ‘ ω ’ can be deduced by requiring that $d\omega \Phi^{1/\omega}$ transforms as a scalar. The resulting transformations are:

$$d\omega' = d\omega [s\det(cw + d)]^2, \quad (2.20)$$

$$\Phi(\omega') = [s\det(cw + d)]^{-2\omega} \Phi(\omega).$$

This means that the Lagrangian should have $\omega = 1$ for the action to be superconformally invariant. An example of this will be the scalar hypermultiplet action.

Charge conjugate expressions of the coordinates can be derived in a way similar to the derivation of superconformal transformations:

$$\mathcal{C} \begin{pmatrix} y & \bar{\theta} \\ \theta & x \end{pmatrix}^\dagger = \begin{pmatrix} -\frac{1}{y} & \frac{\bar{\theta}}{y} \\ \frac{\theta}{y} & x - \frac{\theta \bar{\theta}}{y} \end{pmatrix} \quad (2.21)$$

$$\mathcal{C}(\vartheta)^\dagger = \vartheta - \frac{\theta}{y} \quad (2.22)$$

$$\mathcal{C}(\bar{\vartheta})^\dagger = \bar{\vartheta} + \frac{\bar{\theta}}{y}. \quad (2.23)$$

The conjugate of the hyperfield Φ can be now defined as follows:

$$\mathcal{C}(\Phi)^\dagger = y^{2\omega} [\Phi(\mathcal{C}w)]^\dagger. \quad (2.24)$$

² $d_\theta^4 = d_\theta^2 \bar{d}_\theta^2$, $d_\theta^2 = \frac{1}{2} C_{\beta\alpha} d_\theta^\alpha d_\theta^\beta$, and so on.

D. Internal coordinate

Much of projective hyperspace can be understood by analogy to full $N = 1$ superspace, as a consequence of both having 2 θ ’s and 2 $\bar{\theta}$ ’s. Then, what we have left to understand is the treatment of the internal y -coordinate. The field strengths turn out to be Taylor expandable in y on-shell [15], so their charge conjugates must be Laurent expandable on-shell. Thus, it seems natural to use contour integration:

$$\oint \frac{dy}{2\pi i} \frac{y^m}{y^n} = \delta_{m+1,n}. \quad (2.25)$$

(The factor of $2\pi i$ will be suppressed in what follows.) This makes the y -space effectively compact, as expected for an internal symmetry. It is also a convenient way to constrain a generic hyperfield Φ ’s y -dependence:

$$\begin{aligned} \phi(y)[0^\dagger] &= \oint_{0,y} dy' \frac{1}{y' - y} \Phi(y')[0^\dagger] \\ &= \sum_{n=0}^{\infty} y^n \oint_0 dy' \frac{1}{y'^{n+1}} \Phi(y')[0^\dagger]. \end{aligned} \quad (2.26)$$

Here, $\phi(y)$ has only the non-negative powers of y encoded in the notation $[0^\dagger]$. The coefficients of different powers of y in ϕ matches with the correct ones in $\Phi(y')$ which has all the powers of y denoted by $[0^\dagger]$. Thus, the contour integral acts as an “arctic” projector and ϕ is an arctic hyperfield, being regular at origin.

As for Feynman diagrams in Minkowski space, it is often more convenient, when defining how to integrate around poles (especially when there is more than one integral to evaluate), to move the poles rather than the contour. In this interpretation, instead of having a bunch of integrals over various contours, with the poles for integration over each variable lying on the contour of another variable, we have all integrals over the same contour, with all poles in various different positions near that contour. For our case, the appropriate ‘ ϵ -prescription’ is given by writing the arctic projection of Φ as

$$\begin{aligned} \phi(y_2)[0^\dagger] &= \int dy_1 \frac{1}{y_{12}} \Phi(y_1)[0^\dagger], \\ \frac{1}{y_{12}} &\equiv \frac{1}{y_1 - y_2 + \epsilon(y_1 + y_2)}, \end{aligned} \quad (2.27)$$

at least for the case of any convex contour (e.g., a circular one) about the origin; otherwise, we need to invent a fancier notation. Similarly, an “antarctic” projector with the same ϵ -prescription can be written for an antarctic hyperfield,

$$\bar{\phi}(y_2)[(-1)_\dagger] = \int dy_1 \frac{1}{y_{21}} \Phi(y_1)[0^\dagger] \quad (2.28)$$

where $[(-1)_\dagger]$ denotes $\bar{\phi}$ contains all the negative powers of y .

All these generalities now enable us to properly see them in action.

III. SPECIFIC THEORY

We start with writing the actions for various hypermultiplets and end with enumerating the Feynman rules, which allow us to do all the necessary calculations presented in the next section.

A. Actions

1. Scalar hypermultiplet

For the scalar hypermultiplet, the requirement of Laurent expandability in y turns out to be too weak off-shell; we therefore require that it be Taylor expandable. This “polarity” (i.e. arctic or antarctic) will be the analog of the “chirality” of $N = 1$ supersymmetry. Unlike the $N = 1$ case, we now have an infinite number of auxiliary component fields because of the infinite Taylor expansion in y . The free action can be written in analogy to $N = 1$ as:

$$\mathcal{S}_Y = - \int dx d^4\theta dy \tilde{Y} Y. \quad (3.1)$$

For superconformal invariance and reality, the arctic hyperfield $Y[0^\dagger]$ must have $\omega = \frac{1}{2}$. Its conjugate is an (almost) antarctic hyperfield $\tilde{Y}[1_\dagger] = y[Y(Cw)]^\dagger$. Note that the integral of Y^2 or $\tilde{Y}^2$ would give 0, just as for $N = 1$, but now because of polarity rather than chirality. Also, since there is no analog to the chiral superpotential terms of $N = 1$, there are no renormalizable self-interactions for this hypermultiplet. All its interactions will be through coupling to the vector hypermultiplet.

There is not much to say about the off-shell components: they are just the coefficients of Taylor expansion in y and the θ 's. So, we examine the field equations to see how only a finite number of components survive on-shell. A direct and easy way to accomplish that is to use reflective representation. Using the 4 extra ϑ 's, we can write both the arctic & antarctic hyperfields in terms of an unconstrained (in both y and ϑ) hyperfield:

$$Y(y_2)[0^\dagger] = d_{2\vartheta}^4 \int dy_1 \frac{1}{y_{12}} \Phi(y_1)[0^\dagger] \quad (3.2)$$

$$\tilde{Y}(y_2)[1_\dagger] = d_{2\vartheta}^4 d_{y_2}^2 \int dy_1 \frac{1}{y_{21}} \bar{\Phi}(y_1)[0^\dagger]. \quad (3.3)$$

The y -derivatives appear in (3.3) because: (1) the ant-arctic projection makes “ -1 ” the highest power of y ; (2) the y term in each $d_{2\vartheta}$ increases this to “ 3 ”; and (3) the two y -derivatives decrease this to the correct power of “ -1 ”. Unconstrained variation of the action with respect to $\bar{\Phi}$ (after using the d_{ϑ}^4 to turn $\int d^4\theta$ into $d^8\theta$) then gives the field equations $d_y^2 Y = 0$ (the arctic projection is redundant). On the other hand, variation with respect to Φ kills the antarctic pieces of $\tilde{Y}$, which is the same as

$d_y^2 \tilde{Y} = 0$. Because of superconformal invariance, the rest of the superconformal equations are also satisfied.

Thus, the on-shell component expansion of the scalar hypermultiplet reads³:

$$Y(x, \theta, \bar{\theta}, y) = (A + yB) + \theta\chi + \bar{\theta}\bar{\chi} - \theta\partial B\bar{\theta} \quad (3.4)$$

$$\begin{aligned} \tilde{Y}(x, \theta, \bar{\theta}, y) = y \Big[& \bar{A} - \frac{\theta\partial\bar{A}\bar{\theta}}{y} + \frac{\theta^2\bar{\theta}^2\Box\bar{A}}{y^2} - \frac{\bar{B}}{y} + \frac{\theta^2\bar{\theta}^2\Box\bar{B}}{y^3} \\ & + \frac{\theta}{y} \left(\chi - \frac{\theta\partial\chi\bar{\theta}}{y} \right) + \frac{\bar{\theta}}{y} \left(\bar{\chi} - \frac{\theta\partial\bar{\chi}\bar{\theta}}{y} \right) \Big]. \end{aligned} \quad (3.5)$$

From the last equation, we clearly see that the equations of motion for the complex scalars and the Weyl spinors are satisfied if $d_y^2 \tilde{Y} = 0$ applies.

2. Vector hypermultiplet

Like the scalar hypermultiplet, we look for a description of the vector hypermultiplet in terms of a prepotential defined on projective hyperspace. Again, in analogy to $N = 1$, this should be a real prepotential, rather than a polar one. Because it lacks the polarity restriction, and is thus Laurent expandable in y , it is called “tropical”. Like the scalar hypermultiplet, it will have only a few powers of y surviving on-shell.

Just as for both $N = 0$ & 1 , gauge symmetry is understood as a generalization of global symmetry, so we derive its form by coupling to matter. The straightforward generalization of the $N = 1$ coupling is then given by the action for the scalar hypermultiplet coupled to a vector hypermultiplet background:

$$\mathcal{S}_{Y-V} = - \int dx d^4\theta dy \tilde{Y} e^V Y. \quad (3.6)$$

This coupling fixes the weight of V to be 0:

$$V'(w) = V(w'), \quad \bar{V}(w) \equiv [V(Cw)]^\dagger = V(w) \quad (3.7)$$

The gauge transformations are then

$$Y' = e^{i\Lambda} Y, \quad \tilde{Y}' = \tilde{Y} e^{-i\bar{\Lambda}}, \quad e^{V'} = e^{i\bar{\Lambda}} e^V e^{-i\Lambda} \quad (3.8)$$

where Λ is arctic like Y , but has $\omega = 0$ like V . Thus, $\bar{\Lambda}$ has only nonpositive powers of y , unlike $\tilde{Y}$. Because of the $1/y$'s associated with conjugated coordinates, setting Λ to $\bar{\Lambda}$ would reduce Λ to a real constant, i.e. the global symmetry.

With this gauge invariance, we can examine the on-shell component fields of the vector hypermultiplet. Since Λ contains all non-negative powers of y , and $\bar{\Lambda}$ contains all

³The $\theta\bar{\theta}$ -term in Y can be understood as a consequence of one of the superconformal field equations [15], which schematically reads: $\partial_x \partial_y + \partial_\theta \partial_{\bar{\theta}} = 0$.

nonpositive powers, it might seem that everything can be gauged away, but again the additional $1/y$'s associated with charge conjugation modify things: The $1/y$ in $\mathcal{C}\theta$ increases the number of nongauge components of V with increasing θ , while the $\theta\bar{\theta}/y$ in $\mathcal{C}x$ leads to an x -derivative gauge transformation, again in analogy with the $N = 1$ case. (We can also look at just what Λ gauges away, and then apply “reality” to V .) The result is that, unlike the scalar hypermultiplet (but like the $N = 1$ vector multiplet), V has a finite number of auxiliary fields.

In a Wess-Zumino gauge,

$$V = \frac{1}{y} \left[(\theta A \bar{\theta} + \theta^2 \phi + \bar{\theta}^2 \bar{\phi}) + \bar{\theta}^2 \theta \left(\lambda + \frac{\tilde{\lambda}}{y} \right) + \theta^2 \bar{\theta} \left(\bar{\lambda} + \frac{\tilde{\bar{\lambda}}}{y} \right) + \theta^2 \bar{\theta}^2 \left(\mathcal{D} + \frac{\mathcal{D}_0}{y} + \frac{\bar{\mathcal{D}}}{y^2} \right) \right] \quad (3.9)$$

where the residual gauge invariance is the usual one for the vector A . We thus find, in addition to the expected physical vector (A), a complex scalar (ϕ) and $SU(2)$ doublet of spinors (λ & $\tilde{\lambda}$), there is an $SU(2)$ triplet of auxiliary scalars ($\mathcal{D}$, $\bar{\mathcal{D}}$ & $\mathcal{D}_0$). This same set of fields is found if the vector hypermultiplet is reduced to $N = 1$ supermultiplets, one vector supermultiplet plus one scalar supermultiplet. In the $N = 1$ case, the construction of the vector multiplet action depended on the fact that a spinor derivative could kill the chiral gauge parameter. In the $N = 2$ case, we have arctic and antarctic gauge parameters, and the only way to kill them is by antarctic or arctic projection. This leads to an action of the form

$$S_V = \frac{\text{tr}}{g^2} \int dx d^8\theta \sum_{n=2}^{\infty} \frac{(-1)^n}{n} \times \prod_{i=1}^n \int dy_i \frac{(e^{V_1} - 1) \dots (e^{V_n} - 1)}{y_{12} y_{23} \dots y_{n1}} \quad (3.10)$$

where, $V_i \equiv V(x, \theta, \vartheta, y_i)$. This action is invariant under the following gauge transformation (details are in [1]):

$$\delta(e^V) = i(e^V \Lambda - \bar{\Lambda} e^V) \\ \Rightarrow \delta V = i \left[\frac{V}{2}, \left((\Lambda + \bar{\Lambda}) + \left[\coth \frac{V}{2}, (\Lambda - \bar{\Lambda}) \right] \right) \right]. \quad (3.11)$$

Superconformal invariance of the action might not be obvious, especially because of the nonlocality. The first thing to note is that the full superspace volume element ($\int dx d^8\theta$) is superconformally invariant (because $s\det(g_0) = 1$). Next is to use the results for the superconformal transformations of dw_i and w_{ij} , read from (2.9) and (2.10), to find those for the coordinate y :

$$dy'_i = \frac{dy_i}{(w_i \tilde{c} + \tilde{d})(cw_i + d)} \quad (3.12)$$

$$y'_{ij} = \frac{y_{ij}}{(w_i \tilde{c} + \tilde{d})(cw_j + d)} \quad (3.13)$$

where, the factors $(cw_i + d)$, etc denote the single matrix element corresponding to the y -coordinate. We also use the fact that the other w_{ij} 's vanish as the action is local in these coordinates. The similar transformation factors of dy_i 's & y_{ij} 's then cancel due to the “cyclic” nature of the denominator in SYM action proving its superconformal invariance.

3. Ghost hypermultiplets

The introduction of ghosts follows the usual Becchi-Rouet-Stora-Tyutin (BRST) gauge fixing procedure and is analogous to the case of $N = 1$ at least in the Fermi-Feynman gauge (see Sec. III B for some details.):

$$\begin{aligned} S_{bc} &= -\text{tr} \int dx d^4\theta dy (yb + \bar{b}) \left[\frac{V}{2}, \left(\left(c + \frac{\bar{c}}{y} \right) + \left[\coth \frac{V}{2}, \left(c - \frac{\bar{c}}{y} \right) \right] \right) \right] \\ &= -\text{tr} \int dx d^4\theta dy \left[\bar{b}c + \bar{c}b + (yb + \bar{b}) \frac{V}{2} \left(c + \frac{\bar{c}}{y} \right) + \frac{1}{3} (yb + \bar{b}) \frac{V^2}{4} \left(c - \frac{\bar{c}}{y} \right) + \dots \right]. \end{aligned} \quad (3.14)$$

We can also choose a nonlinear gauge like the Gervais-Neveu gauge in which the ghost action would be simplified to:

$$\begin{aligned} S_{bc} &= -\text{tr} \int dx d^4\theta dy (yb + \bar{b}) \left[e^V c - \frac{\bar{c}}{y} e^V \right] \\ &= -\text{tr} \int dx d^4\theta dy \left[y b e^V c + \bar{c} e^V b + \bar{b} e^V c + \frac{1}{y} \bar{c} e^V \bar{b} \right]. \end{aligned} \quad (3.15)$$

There does not seem to be any real advantage of this gauge (e.g. to show the nonrenormalization of g in $N = 4$ SYM is not that straightforward), apart from the absence of “weird” numerical factors coming from the expansion of $\coth(x)$ in the case of Fermi-Feynman gauge. So we will use action (3.14) in all the calculations presented later.

B. Propagators

1. Scalar

We add source terms to the quadratic action of Y and convert the $d^4\theta$ integral to $d^8\theta$ integral by rewriting Y 's using Eqs. (3.2) and (3.3)⁴:

⁴Writing Y instead of Φ does not make a difference here.

$$\begin{aligned}
\mathcal{S}_{Y-J} &= - \int dx d^4\theta dy [\tilde{Y}Y + \bar{J}Y + \tilde{Y}J] \\
&= - \int dx d^8\theta \int dy_1 \left[d_{y_1}^2 \int dy_3 \frac{\tilde{Y}_3}{y_{13}} d_{1\theta}^4 \int dy_2 \frac{Y_2}{y_{21}} \right. \\
&\quad \left. + \bar{J}_1 \int dy_2 \frac{Y_2}{y_{21}} + d_{y_1}^2 \int dy_3 \frac{\tilde{Y}_3}{y_{13}} J_1 \right]. \quad (3.16)
\end{aligned}$$

The sources J & $\bar{J}$ are generic projective hyperfields with $\omega = \frac{1}{2}$. Now, the modified equations of motion of $\tilde{Y}$ & Y can be derived from above and (after some integration by parts) they read:

$$\begin{aligned}
\int dy_1 \frac{d_{1\theta}^4 d_{y_1}^2 Y_1}{y_{13}} &= - \int dy_1 d_{1\theta}^4 d_{y_1}^2 \left(\frac{1}{y_{13}} \right) J_1 \\
\Rightarrow \square Y_3 &= - d_{3\theta}^4 \int dy_1 \frac{2J_1}{y_{13}^3}. \quad (3.17)
\end{aligned}$$

$$\text{Similarly, } \square \tilde{Y}_2 = - d_{2\theta}^4 \int dy_1 \frac{2\bar{J}_1}{y_{21}^3}. \quad (3.18)$$

Plugging the Eqs. (3.17) and (3.18) back in action (3.16), we get:

$$\begin{aligned}
\mathcal{S}_{Y-J} &= \frac{1}{2} \int dx d^8\theta dy_1 \left[\bar{J}_1 \frac{1}{\frac{1}{2}\square} \int dy_2 \frac{J_2}{y_{21}^3} \right. \\
&\quad \left. + \frac{1}{\frac{1}{2}\square} \int dy_2 \frac{\bar{J}_2}{y_{12}^3} J_1 \right] \\
&= \int dx d^8\theta dy_1 dy_2 \left[\bar{J}_1 \frac{1}{y_{21}^3} \frac{1}{\frac{1}{2}\square} J_2 \right]. \quad (3.19)
\end{aligned}$$

This gives us the following scalar propagator:

$$\langle Y(1) \tilde{Y}(2) \rangle = - \frac{d_{1\theta}^4 d_{2\theta}^4 \delta^8(\theta_{12})}{y_{21}^3} \frac{\delta(x_{12})}{\frac{1}{2}\square}. \quad (3.20)$$

2. Vector

Gauge-fixing of the vector hypermultiplet action looks similar to the $N = 1$ case, in the same sense that the scalar hypermultiplet action does. The main modifications are that now $d^4\theta$ is projective, there is also dy , the ghosts and Nakanishi-Lautrup fields are projective arctic/antarctic fields instead of chiral/antichiral ones. The y -dependence of ghosts c & $\bar{c}$ is $[0^1]$ & $[0_1]$; antighosts b & $\bar{b}$ is $[0^1]$ & $[2_1]$ and NL fields B & $\bar{B}$ is $[0^1]$ & $[2_1]$. We redefine the conjugates so that their y -dependence is similar to $\tilde{Y}$:

$$\begin{aligned}
\bar{c}[0_1] &\rightarrow \frac{1}{y} \bar{c}[1_1]; \\
\bar{b}[2_1] &\rightarrow y \bar{b}[1_1]; \\
\bar{B}[2_1] &\rightarrow y \bar{B}[1_1]. \quad (3.21)
\end{aligned}$$

We choose the following gauge-fixing function:

$$V_{\text{gf}} = \int dx d^4\theta dy (yb + \bar{b})V \quad (3.22)$$

$$\delta V_{\text{gf}} = \int dx d^4\theta dy \left[(yB + \bar{B})V + (yb + \bar{b})\delta V\left(c, \frac{\bar{c}}{y}\right) \right]. \quad (3.23)$$

The second term gives $\mathcal{S}_{bc}$ in Fermi-Feynman gauge⁵ (Eq. (3.14)). The first term along with a gauge-averaging term (kinetic term for NL field) gives us the gauge-fixing action:

$$\mathcal{S}_{\text{gf}} = \frac{\text{tr}}{g^2} \int dx d^4\theta dy \left[-\bar{B} \frac{1}{\square} B + (yB + \bar{B})V \right] \quad (3.24)$$

$$\Rightarrow \mathcal{S}_{\text{gf}} = \frac{\text{tr}}{2g^2} \int dx d^8\theta dy_1 dy_2 V_1 \left[\frac{y_2}{y_{12}^3} + \frac{y_1}{y_{21}^3} \right] V_2. \quad (3.25)$$

The final expression for $\mathcal{S}_{\text{gf}}$ follows from similar manipulations employed in deriving Eq. (3.19), i.e. by integrating out B & $\bar{B}$ using their equations of motion.

We now combine the terms quadratic in V from the above equation and Eq. (3.10) to get:

$$\begin{aligned}
\mathcal{S}_V^{(2)} + \mathcal{S}_{\text{gf}}^{(2)} &= - \frac{\text{tr}}{2g^2} \int dx d^4\theta dy_1 dy_2 V_1 \frac{1}{y_{12}^2} \\
&\quad \times \left[1 - \frac{y_2}{y_{12}} - \frac{y_1}{y_{21}} \right] d_{1\theta}^4 V_2 \\
&= \frac{\text{tr}}{2g^2} \int dx d^4\theta dy_1 dy_2 V_1 \frac{1}{y_{12}^2} \left[\frac{y_1 + y_2}{2} \delta(y_{12}) \right] y_{12}^2 \\
&\quad \times \left(\frac{1}{2}\square + \mathcal{O}(y_{12}) \right) V_2 \\
&= \frac{\text{tr}}{2g^2} \int dx d^4\theta dy y \frac{V \square V}{2}. \quad (3.26)
\end{aligned}$$

This gives the following vector propagator:

$$\langle V(1)V(2) \rangle = d_{1\theta}^4 \delta^8(\theta_{12}) \frac{\delta(y_{12})}{y_1} \frac{\delta(x_{12})}{\frac{1}{2}\square}. \quad (3.27)$$

3. Ghosts

The derivation of ghost propagators proceeds along similar lines to that of the scalar propagator and the results are:

$$\langle \bar{b}(1)c(2) \rangle = \langle \bar{c}(1)b(2) \rangle = \frac{d_{1\theta}^4 d_{2\theta}^4 \delta^8(\theta_{12})}{y_{12}^3} \frac{\delta(x_{12})}{\frac{1}{2}\square}, \quad (3.28)$$

⁵Choosing $(e^V - 1)$ instead of V in V_{gf} gives the ghost action (3.15).

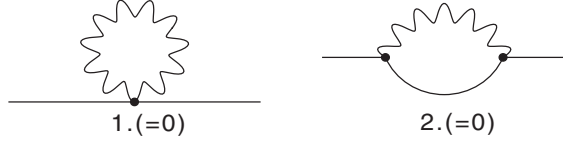


FIG. 1. Scalar self-energy diagrams at 1-loop.

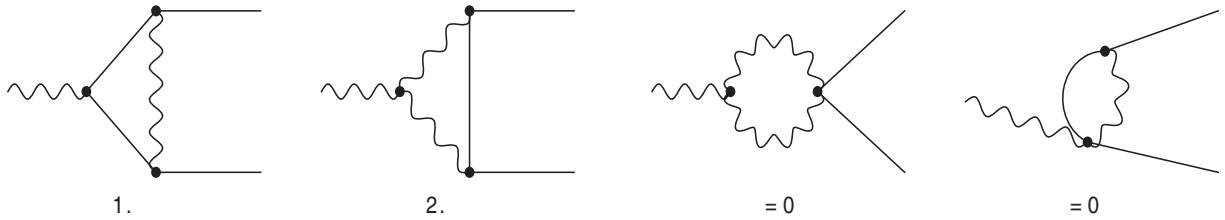
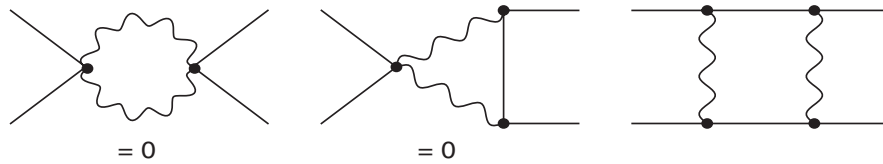
- (1) 1V-propagator: Remove d_θ^4 from the vector propagator to get the $d^8\theta$ measure. This leaves no d_θ 's to kill the $\delta^8(\theta_{12})$, so this diagram vanishes. Such tadpole diagrams (even multihoop diagrams containing these as subdiagrams) always vanish, so we will not consider these anymore in what follows.
- (2) 1V- & 1Y-propagators: Remove two d_θ^4 's from these propagators to complete the two $d^4\theta$ measures. This means there are not enough (in fact, only 4) d_θ 's left to kill one of the $\delta^8(\theta_{12})$, so this diagram also vanishes.

This means that the scalar hyperfield is not renormalized, which is obvious from the fact that its action is over only the projective hyperspace but the Feynman diagrams give contributions over full hyperspace. In other words, scalar hypermultiplet action (coupled to vector hypermultiplet, as shown below) is not renormalized at any loop order.

2. $\bar{Y}VY$

There are four diagrams in this case as shown in Fig. 2. Two of these diagrams vanish because of d -algebra similar to the self-energy case. The other two are evaluated below:

- (1) 1V- & 2Y-propagators: This diagram has enough (8, at last) d_θ 's to kill one of the $\delta(\theta)$ functions so that two θ -integrals can now be done. However, this generates only a y_{12}^4 -factor without any momentum factors in the numerator, which makes this diagram

FIG. 2. $\bar{Y}VY$ diagrams at 1-loop.FIG. 3. $\bar{Y}Y\bar{Y}Y$ diagrams at 1-loop.

power-counting finite and the explicit finite result reads:

$$-\frac{c_A}{2} \int \frac{d^4 k}{(2\pi)^4} \frac{1}{\frac{1}{2}k^2 \frac{1}{2}(k+p_2)^2 \frac{1}{2}(k-p_1)^2} \times \int d^8\theta \int \frac{dy_{1,2}}{y_2} \frac{\bar{Y}_2(p_2)V_1(p_1)Y_2(p_3)}{y_{12}y_{21}}, \quad (4.1)$$

where p_i 's are the external momenta.

- (2) 2V- & 1Y-propagators: Applying similar maneuvers as above, we conclude that this diagram is also finite:

$$-\mathcal{A}_3(p_2, -p_1) \times \frac{c_A}{2} \int d^8\theta \int \frac{dy_{1,2,3}}{y_2 y_3} \times \frac{\bar{Y}_2(p_2)V_1(p_1)Y_3(p_3)}{y_{12}y_{31}}, \quad (4.2)$$

where $\mathcal{A}_3(p_2, -p_1)$ is just the momentum integral of Eq. (4.1).

In fact, all hoop diagrams for any $\bar{Y}V^nY$ vertices are finite because of the noncancellation of “sufficient” momentum factors in the denominator.

3. $\bar{Y}Y\bar{Y}Y$

Such a vertex does not appear in the action and hence, the 1-loop diagrams (Fig. 3) contributing to this vertex can not be divergent.

Out of the three diagrams, two vanish due to d -algebra and the remaining box-diagram can be evaluated in a straightforward manner to give a finite result:

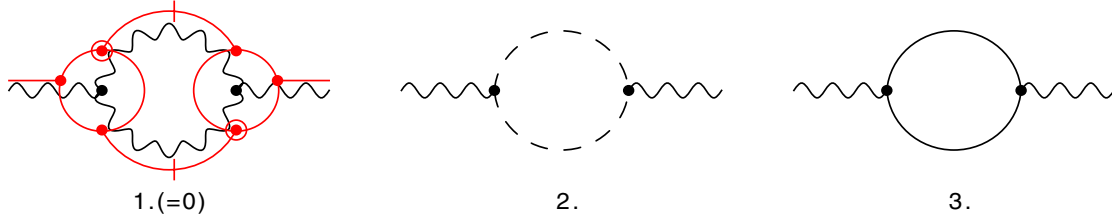


FIG. 4 (color online). Vector self-energy diagrams at 1-loop.

$$\sim \int \frac{d^4 k}{(2\pi)^4} \frac{1}{\frac{1}{2}k^2 \frac{1}{2}(k+p_2)^2 \frac{1}{2}(k+p_2+p_3)^2 \frac{1}{2}(k-p_1)^2} \times \int d^8 \theta \int \frac{dy_{1,2}}{y_1 y_2} \frac{\bar{Y}_1(p_1) Y_1(p_2) \bar{Y}_2(p_3) Y_2(p_4)}{y_{12} y_{21}}. \quad (4.3)$$

4. Vector Self-energy

There are three classes of diagrams contributing to the self-energy corrections with different hyperfields (vector, ghosts or scalar) running inside the loop as shown in Fig. 4:

- (1) *V*-propagators: There are a couple of diagrams (not shown explicitly in Fig. 4) which have at least one $V_1^2 V_2$ -type vertex and they vanish trivially due to the presence of expressions like $y^3 \delta(y)$ or $y^4 \delta(y)^2$. This is a generic feature of 1-loop (at least) diagrams containing such vertices and these will not be considered here anymore.

The diagram which has both vertices of $V_1 V_2 V_3$ -type (shown explicitly in Fig. 4⁸) also vanishes but in a different way. After doing the d -algebra and integrating the two $\delta(y)$'s, we are left with the following y -integrals:

$$\begin{aligned} & \int dy_{1,2,a,b} \frac{V_1 V_2 y_{ab} y_{ba}}{y_a y_b y_{1b} y_{a1} y_{2a} y_{b2}} \\ &= \int dy_{1,2} \frac{V_1 V_2}{y_{12} y_{21}} \int dy_{a,b} \left(\frac{1}{y_{a1}} + \frac{1}{y_{2a}} \right) \left(\frac{1}{y_{1b}} + \frac{1}{y_{b2}} \right) \\ & \quad \times \left(2 - \frac{y_a}{y_b} - \frac{y_b}{y_a} \right) \\ &= \int dy_{1,2} \frac{V_1 V_2}{y_{12} y_{21}} \left(2 - \frac{y_1}{y_1} - \frac{y_2}{y_2} \right) = 0. \end{aligned}$$

- (2) (b, c) -propagators: There are four diagrams with different combinations of ghost propagators and vertices. All of them combine to give (after relevant d -algebra)⁹:

⁸The red (straight) lines over the wavy lines depict the 'y-dependence' of the diagram following the rules given in the Appendix.

⁹ $V \rightarrow gV$ in rest of the paper.

$$\begin{aligned} & \mathcal{A}_2(p) \times 2 \frac{1}{2} c_A \frac{g^2}{4} \int d^8 \theta \int dy_{1,2} \frac{V_1 V_2}{y_{12} y_{21}} \\ & \quad \times \left(1 + \frac{y_1}{y_2} + \frac{y_2}{y_1} + 1 \right) \\ &= \mathcal{A}_2(p) \times \frac{c_A}{4} g^2 \int d^8 \theta \int dy_{1,2} \frac{V_1 V_2}{y_{12} y_{21}} \\ & \quad \times \left(\frac{-y_{12} y_{21} + 4 y_1 y_2}{y_1 y_2} \right) \\ &= \mathcal{A}_2(p) \times c_A g^2 \int d^8 \theta \int dy_{1,2} \frac{V_1 V_2}{y_{12} y_{21}}. \quad (4.4) \end{aligned}$$

The last line follows entirely from the second term in parentheses of the previous line. This is because the first term with no y_{12} 's in the integrand vanishes since $d^8 \theta$ kills such projective integrands. Also, $\mathcal{A}_2(p)$ is the divergent integral and is evaluated using dimensional regularization to give:

$$\begin{aligned} \mathcal{A}_2(p) &= \int \frac{d^D k}{(2\pi)^D} \frac{1}{\frac{1}{2}k^2 \frac{1}{2}(k+p)^2} \\ &= \frac{1}{4\pi^2} \left[\frac{1}{\epsilon} - \gamma_E - \ln\left(\frac{p^2}{\mu^2}\right) \right], \\ \frac{1}{\epsilon} &= \frac{2}{4-D}. \end{aligned}$$

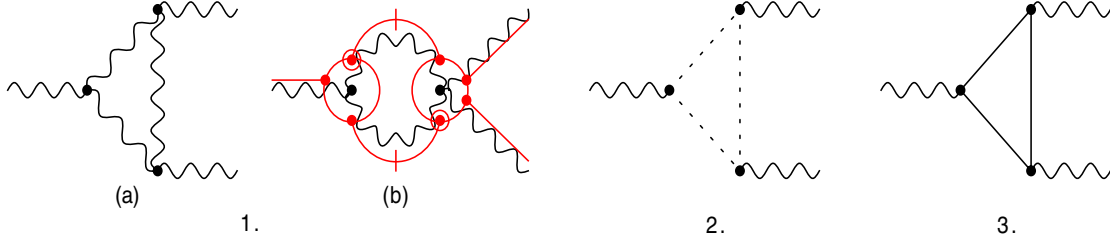
- (3) *Y*-propagators: The calculation for this single diagram is similar to that of the ghost which gives:

$$- \mathcal{A}_2(p) \times c_R g^2 \int d^8 \theta \int dy_{1,2} \frac{V_1 V_2}{y_{12} y_{21}}. \quad (4.5)$$

5. $V_1 V_2 V_3$

Similar to the vector self-energy case, three classes of diagrams contribute in this case also as shown in Fig. 5. We give only the final results after doing the d -algebra and y -calculus in what follows.

- (1) *V*-propagators: There are two diagrams in this class and both are nonzero. We use the notation $\overleftrightarrow{\frac{y_i}{y_j}}$ to denote the sum of permutations of $\frac{y_i}{y_j}$ -factors over all possible values of i , e.g. $\overleftrightarrow{\frac{y_1}{y_2}} = \left(\frac{y_1}{y_2} + \frac{y_2}{y_3} + \frac{y_3}{y_1} \right)$.

FIG. 5 (color online). $V_1 V_2 V_3$ diagrams at 1-loop.

- (a) $(VVV)^3$ vertices: The full (divergent & finite) contribution of this diagram reads:

$$\begin{aligned}
 & -\frac{c_A}{2} g^3 \int d^8 \theta \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \\
 & \times \left[\mathcal{A}_2(p_3) \left(-3 + \left\downarrow \frac{y_1}{y_2} \right\downarrow \right) + p_2^2 \mathcal{A}_3(p_2, -p_1) \right. \\
 & \times \left. \left(1 + \left\downarrow \frac{y_1}{y_2} - \frac{1}{3} \left(\frac{y_{31}}{y_1} \right)^2 \right\downarrow \right) \right]. \quad (4.6)
 \end{aligned}$$

- (b) $(VVVV) - (VVV)$ vertices: The (wavy line) diagram looks like contributing only to the $V_1 V_2^2$ vertex term in the action but due to the 4-point vertex, this diagram also contributes to $V_1 V_2 V_3$ vertex as shown explicitly by the ‘y-dependence’ in Fig. 5. We will be giving the results for diagrams with all (external) V ’s at distinct y ’s only since the results for other diagrams follow from those of the self-energy case. This particular diagram gives a very simple contribution similar to the self-energy case:

$$\begin{aligned}
 & -\mathcal{A}_2(p_3) \times \frac{1}{2} \frac{c_A}{2} g^3 \int d^8 \theta \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \\
 & \times \left(3 - \left\downarrow \frac{y_1}{y_2} \right\downarrow \right). \quad (4.7)
 \end{aligned}$$

- (2) (b, c) -propagators: There are eight diagrams with different combinations of ghost propagators and vertices. All of them combine to give the following part containing the divergence:

$$\begin{aligned}
 & \mathcal{A}_2(p_3) \times 2 \frac{c_A}{2} \frac{g^3}{8} \int d^8 \theta \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \\
 & \times \left(1 + \left\downarrow \frac{y_1}{y_2} + \frac{y_1}{y_3} \right\downarrow + 1 \right) \\
 & = \mathcal{A}_2(p_3) \times \frac{c_A}{8} g^3 \int d^8 \theta \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \\
 & \times 2 \left(1 + \left\downarrow \frac{y_1}{y_2} \right\downarrow - \frac{y_{12} y_{23} y_{31}}{2 y_1 y_2 y_3} \right) \quad (4.8)
 \end{aligned}$$

where the last term in the parentheses does not contribute as in the case of self-energy diagram

but the last term does contribute in the remaining finite part given below:

$$\begin{aligned}
 & p_2^2 \mathcal{A}_3(p_2, -p_1) \times \frac{c_A}{4} g^3 \int d^8 \theta \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \\
 & \times \frac{1}{3} \left\downarrow \left(\frac{y_{12}}{y_{31}} \right)^2 \right\downarrow \left(1 + \left\downarrow \frac{y_1}{y_2} - \frac{y_{12} y_{23} y_{31}}{2 y_1 y_2 y_3} \right\downarrow \right). \quad (4.9)
 \end{aligned}$$

- (3) Y -propagators: The calculation for this single diagram is again straightforward and gives as expected:

$$\begin{aligned}
 & -c_R g^3 \int d^8 \theta \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \\
 & \times \left[\mathcal{A}_2(p_3) + p_2^2 \mathcal{A}_3(p_2, -p_1) \frac{1}{3} \left\downarrow \left(\frac{y_{12}}{y_{31}} \right)^2 \right\downarrow \right]. \quad (4.10)
 \end{aligned}$$

6. $V_1 V_2 V_3 V_4$

The calculations in this case are similar to the earlier ones except for an increase in the number of y -integrals to be evaluated. Before we proceed further, we make a group theoretical comment. None of the 4-point diagrams generate terms proportional to

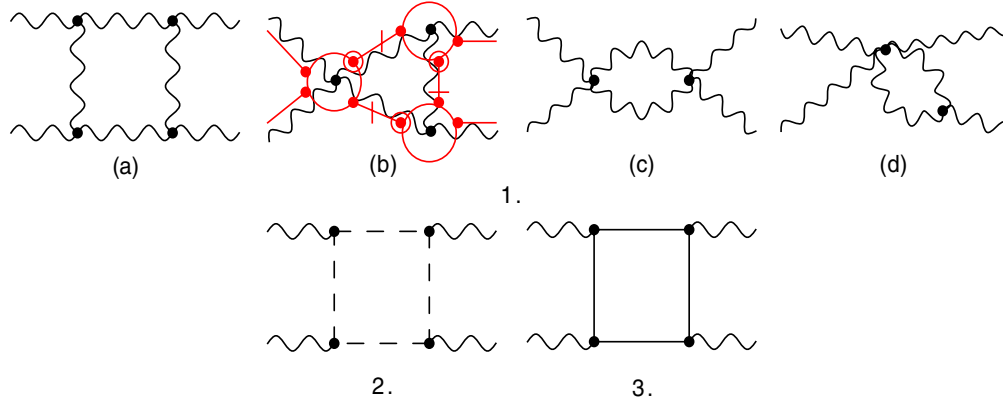
$$f_{ipq} f_{jqr} f_{krs} f_{lsp} V_1^i V_2^j V_3^k V_4^l \equiv G_{ijkl} V_1^i V_2^j V_3^k V_4^l,$$

which do not appear in the SYM action.¹⁰ This was, however, not the case when similar calculations were done using $N = 1$ supergraph rules in [11] and a nonlinear (cubic) wavefunction renormalization (proportional to $GVVV$) was required to keep the effective action renormalizable as predicted in [10].

We do not encounter this feature because of the ‘‘antisymmetry’’ of the y_{ab} factors, which enforces the Jacobi identity leading (in this particular case) to this useful identity:

$$G_{ijkl} - G_{ijlk} = \frac{c_A}{2} f_{ijp} f_{klp} \equiv \frac{c_A}{2} \text{---} \text{---} \text{---}.$$

¹⁰Recall from subsection III C that the V^4 term appearing in the action is proportional to $f_{ijp} f_{klp} V_1^i V_2^j V_3^k V_4^l$.

FIG. 6 (color online). $V_1 V_2 V_3 V_4$ diagrams at 1-loop.

Hence, all the 4-point diagrams end up producing the V^4 term present in the SYM action and the usual renormalization procedure is applicable. (One more reason is that ‘ gV ’ is *not* renormalized, as explained later.) Now, we enumerate the complete results for the usual three classes of diagrams shown in Fig. 6:

- (1) V -propagators: There are four nonzero diagrams in this class. After doing the relevant algebra and including the permutations of $\frac{y_i}{y_j}$ -factors, we get:

(a) $(VVV)^4$ vertices:

$$\begin{aligned}
 & -\frac{c_A}{2} g^4 \int d^8 \theta \int dy_{1,2,3,4} \frac{V_1 V_2 V_3 V_4}{y_{12} y_{23} y_{34} y_{41}} \left[(\mathcal{A}_2(p_4) - p_2^2 \mathcal{A}_3(-p_3, p_4)) \left(\frac{1}{2} \left\{ \frac{y_1}{y_2} + \frac{y_1}{y_4} - \frac{y_1}{y_3} \right\} \right) + \mathcal{A}_3(-p_3, p_4) \right. \\
 & \times \left\{ p_1^2 \left(\frac{1}{4} \left\{ 3 \frac{y_1}{y_2} - 2 \frac{y_1}{y_3} - \frac{y_3^2}{y_1^2} - \frac{y_3^2}{y_1 y_4} + \frac{y_3^3}{y_1^2 y_4} \right\} \right) + p_2^2 \left(-2 + \frac{1}{4} \left\{ 4 \frac{y_1}{y_2} - 3 \frac{y_1}{y_3} + \frac{y_3 y_4}{y_1^2} - \frac{y_4^2}{y_1^2} + \frac{y_4^2}{y_1 y_2} \right\} \right) \right. \\
 & + 2 p_1 \cdot p_2 \left(2 - \frac{1}{4} \left\{ 4 \frac{y_1}{y_2} - \frac{y_1}{y_3} + \frac{y_3^2}{y_1^2} - \frac{y_3^2}{y_1 y_4} - \frac{y_3 y_4}{y_1^2} \right\} \right) \left. \right] + p_1^2 (p_1 + p_2)^2 \mathcal{A}_4(p_2, p_2 + p_3, -p_1) \\
 & \times \left(-4 + \frac{1}{4} \left\{ 5 \frac{y_1}{y_2} + 2 \frac{y_1}{y_3} - \frac{y_3^2}{y_1^2} - \frac{3 y_3^2}{y_1 y_4} + \frac{y_3^3}{y_1^2 y_4} \right\} \right) \left. \right] \quad (4.11)
 \end{aligned}$$

(b) $(VVVV)-(VVV)^2$ vertices:

$$-\frac{c_A}{2} g^4 \int d^8 \theta \int dy_{1,2,3,4} \frac{V_1 V_2 V_3 V_4}{y_{12} y_{23} y_{34} y_{41}} \left[\mathcal{A}_2(p_4) \left(-8 + 2 \left\{ \frac{y_1}{y_3} \right\} \right) + p_3^2 \mathcal{A}_3(-p_3, p_4) \left\{ \frac{y_{14}}{y_{12}} \frac{y_{24}^3}{y_2^2 y_4} \right\} \right] \quad (4.12)$$

(c) $(VVVV)^2$ vertices:

$$-\mathcal{A}_2(p_4) \times \frac{1}{2} \frac{c_A}{2} g^4 \int d^8 \theta \int dy_{1,2,3,4} \frac{V_1 V_2 V_3 V_4}{y_{12} y_{23} y_{34} y_{41}} \left(4 - \frac{1}{2} \left\{ \frac{y_1}{y_2} + \frac{y_1}{y_4} \right\} \right) \quad (4.13)$$

(d) $(VVVVV)-(VVV)$ vertices:

$$-\mathcal{A}_2(p_4) \times \frac{1}{2} c_A g^4 \int d^8 \theta \int dy_{1,2,3,4} \frac{V_1 V_2 V_3 V_4}{y_{12} y_{23} y_{34} y_{41}} \left(4 - \left\{ \frac{y_1}{y_3} \right\} \right) \quad (4.14)$$

- (2) (b, c) -propagators: There are 16 diagrams that combine to give (after dropping the term with a projective integrand):

$$\begin{aligned}
& \frac{c_A}{16} g^4 \int d^8\theta \int dy_{1,2,3,4} \frac{V_1 V_2 V_3 V_4}{y_{12} y_{23} y_{34} y_{41}} \left[(\mathcal{A}_2(p_4) - p_2^2 \mathcal{A}_3(-p_3, p_4)) \left(2 \uparrow \frac{y_1}{y_2} + \frac{y_1}{y_4} \uparrow \right) \right. \\
& + \left\{ \mathcal{A}_3(-p_3, p_4) \frac{1}{4} \left(p_1^2 \uparrow \left(\frac{y_{24}}{y_{41}} \right)^2 \uparrow + p_2^2 \uparrow \left(\frac{y_{13}}{y_{41}} \right)^2 \uparrow - 2 p_1 \cdot p_2 \uparrow \frac{y_{23}}{y_{14}} + \frac{y_{12}}{y_{41}} \frac{y_{34}}{y_{41}} \uparrow \right) + p_1^2 (p_1 + p_2)^2 \mathcal{A}_4(p_2, p_2 + p_3, -p_1) \right. \\
& \left. \left. \times \frac{1}{4} \uparrow \left(\frac{y_{12}}{y_{41}} \right)^2 \uparrow \right) \left(2 \uparrow \frac{y_1}{y_2} + \frac{y_1}{y_4} \uparrow + \frac{y_{12} y_{23} y_{34} y_{41}}{y_1 y_2 y_3 y_4} \right) \right] \quad (4.15)
\end{aligned}$$

- (3) Y-propagators: Without doing any new calculations, we can write the result, which is similar to Eq. (4.15):

$$\begin{aligned}
& -c_R g^4 \int d^8\theta \int dy_{1,2,3,4} \frac{V_1 V_2 V_3 V_4}{y_{12} y_{23} y_{34} y_{41}} \\
& \times \left[(\mathcal{A}_2(p_4) - p_2^2 \mathcal{A}_3(-p_3, p_4)) + \mathcal{A}_3(-p_3, p_4) \right. \\
& \times \frac{1}{4} \left(p_1^2 \uparrow \left(\frac{y_{24}}{y_{41}} \right)^2 \uparrow + p_2^2 \uparrow \left(\frac{y_{13}}{y_{41}} \right)^2 \uparrow \right. \\
& - 2 p_1 \cdot p_2 \uparrow \frac{y_{23}}{y_{14}} + \frac{y_{12}}{y_{41}} \frac{y_{34}}{y_{41}} \uparrow \left. \right) + p_1^2 (p_1 + p_2)^2 \\
& \left. \times \mathcal{A}_4(p_2, p_2 + p_3, -p_1) \frac{1}{4} \uparrow \left(\frac{y_{12}}{y_{41}} \right)^2 \uparrow \right]. \quad (4.16)
\end{aligned}$$

B. 1-hoop β -function

The divergences proportional to the terms in the vector hypermultiplet's action are absorbed via wavefunction (V) and coupling constant (g) renormalization following the usual well-known procedure.

$$Z\text{-factor for } V: V_R = \sqrt{Z_V} V \Rightarrow Z_V^{(1)} = Z_2^{(1)} \quad (4.17)$$

$$Z\text{-factor for } g: g_R = Z_g g \mu^\epsilon \Rightarrow Z_g^{(1)} = Z_3^{(1)} (Z_V^{(1)})^{-(3/2)} \quad (4.18)$$

where, the $Z_n^{(1)}$'s are the Z-factors for corresponding n -point vertex terms in the action, i.e. $\mathcal{S}(V_R^n) = Z_n \mathcal{S}(V^n)$. To figure these out, we combine the divergent term of $\mathcal{A}_2$ occurring in all n -point functions. The result is:

$$\begin{aligned}
& 2\text{-point (4.4 \& 4.5)}: \frac{(c_A - c_R) g^2}{4\pi^2 \epsilon} \int d^8\theta \int dy_{1,2} \frac{V_1 V_2}{y_{12} y_{21}}; \\
& 3\text{-point (4.6 - 4.10)}: \frac{(c_A - c_R) g^3}{4\pi^2 \epsilon} \int d^8\theta \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}}; \\
& 4\text{-point (4.11 - 4.16)}: \frac{(c_A - c_R) g^4}{4\pi^2 \epsilon} \int d^8\theta \int dy_{1,2,3,4} \frac{V_1 V_2 V_3 V_4}{y_{12} y_{23} y_{34} y_{41}}; \\
& \Rightarrow Z\text{-factors for Vertices: } Z_2^{(1)} = Z_3^{(1)} = Z_4^{(1)} = 1 + \frac{(c_A - c_R) g^2}{4\pi^2 \epsilon} \quad (4.19)
\end{aligned}$$

Finally, plugging Eq. (4.19) in (4.17) and (4.18), we get:

$$Z_V^{(1)} = 1 + \frac{(c_A - c_R) g^2}{4\pi^2 \epsilon}; \quad (4.20)$$

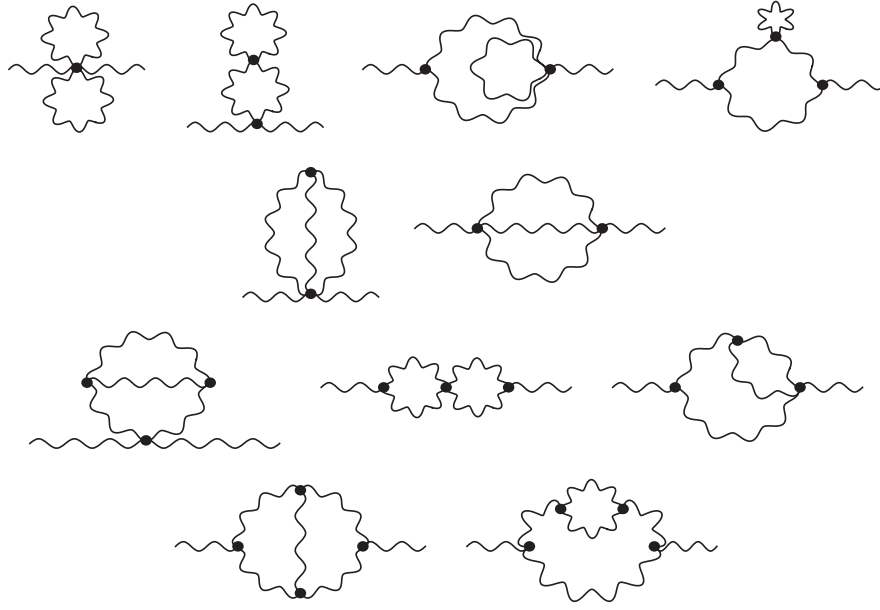
$$Z_g^{(1)} = 1 - \frac{(c_A - c_R) g^2}{8\pi^2 \epsilon}. \quad (4.21)$$

Using the coupling constant renormalization factor, the 1-loop β -function for $N = 2$ SYM coupled to matter in representation R is easily calculated:

$$\begin{aligned}
\beta_{N=2}^{(1)} &= g^3 \frac{\partial(\epsilon Z_g^{(1)})}{\partial g^2} = -\frac{(c_A - c_R) g^3}{8\pi^2} \\
&\left(= -\frac{(2n - c_R) g^3}{8\pi^2} \quad \text{for } \text{SU}(n) \right). \quad (4.22)
\end{aligned}$$

For $N = 4$ SYM, it is trivial to see that the beta-function vanishes at 1-loop since the scalar hypermultiplet is in adjoint representation (so $c_R = c_A$), implying

$$\beta_{N=4}^{(1)} = 0.$$

FIG. 7. Vector self-energy diagrams at 2-loops with only V -propagators.FIG. 8. Vector self-energy diagrams at 2-loops including b , c & Y -propagators.

C. 2-loops Finiteness

We recall that any n -point function involving external scalar hyperfields (including ghosts) can not be divergent and hence the hyperfields b , c & Y and other terms in actions (3.6) and (3.14) are not renormalized. Thus, we need to calculate just the vector self-energy corrections to compute the β -function at two-loops. We can read off the Z_g -factor from $g\bar{b}Vc$ (or $g\bar{Y}VY$ in case of $N = 4$ SYM) vertex at 2-loops (which is true even in the case of 1-loop as can be easily checked.):

$$Z_g^{(2)} = (Z_V^{(2)})^{-(1/2)}. \quad (4.23)$$

In other words, gV is not renormalized which means that the vector hyperfield V can not have any nonlinear renormalization since the coupling constant g is always linearly renormalized. This is the same result as in the background field formalism as far as renormalization is concerned.

There are a lot of diagrams to consider at 2-loops (at first sight) but their evaluation is not any more difficult than

those at 1-loop. First, we consider the 11 diagrams shown in Fig. 7 which have only vector propagators. The first two rows in the figure show diagrams that vanish due to d -algebra (i.e. insufficient number of $d_{a\bar{a}}^4$'s). The remaining 5 diagrams require some y -calculus and we find that none of their divergent terms survive and only the last two of them have finite terms. The vanishing of divergences for these two diagrams is shown in the appendix.

Second, there are a lot more diagrams having ghost & scalar propagators, but only 4 classes of such diagrams (Fig. 8) need to be examined in “detail”. The rest of such diagrams vanish either due to the d -algebra or emergence of $y\delta(y)$ (even $y^2\delta(y)$) factor (mainly in diagrams having only $\bar{b}Vc$ -type vertices). Again, after doing some y -calculus we see that these four classes of diagrams also do not have any divergences. Thus, there are no divergent vector self-energy corrections at 2-loops (i.e. $Z_V^{(2)} = 1$) and hence for both $N = 2$ SYM coupled to matter in any representation and $N = 4$ SYM,

$$\beta^{(2)} \sim \partial_{g^2}(Z_g^{(2)}) = 0.$$

V. CONCLUSION

We investigated one & two-loop(s) diagrams for $N = 2$ massless vector & scalar hypermultiplets directly in projective hyperspace for the cases of 2, 3, & 4-point functions. We found that the effective action receives only 1-loop divergent corrections, which have the same form as the classical action. We also calculated all the 1-loop finite pieces of the diagrams. Some of them are similar to the classical action modulo the momentum factors whereas others have extra y -factors, whose ‘nonlinearity’ prevents any simplification of the results. In spite of that, we derived the well-known result that the $N = 2$ SYM coupled to matter is 2-loops finite. These calculations also enable us to show that $N = 4$ SYM is finite at one & two-loop(s).

Similar calculations can be done with the Harmonic hyperspace Feynman rules and the procedure is not that different or difficult. However, the repeated use of harmonic derivatives (d_y & $d_{\bar{y}}$) to simplify the SU(2) invariant harmonics in order to do the SU(2) integrals is definitely cumbersome compared to “evaluating” some contour integrals on a complex plane as in the Projective hyperspace.

Our results like the linear wavefunction renormalization and the nonrenormalization of ‘ gV ’ have the same simplicity as expected from a background field formalism. So, it would be more interesting to construct a background field formalism for projective hyperspace that would definitely simplify these calculations and also (hopefully) give us insights into the origin of the vector hyperfield, V .

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APPENDIX: y -CALCULUS

1. Important identities

These “simple” identities are useful for proving gauge invariance of the vector action, deriving component action of $N = 2$ SYM, deriving vector propagator and evaluating y -integrals for Feynman diagrams:

$$\frac{1}{y_{ij}y_{jk}} = \frac{1}{y_{ik}} \left(\frac{1}{y_{ij}} + \frac{1}{y_{jk}} \right) \quad (A1)$$

$$\frac{1}{y_{12}} + \frac{1}{y_{21}} = -2\pi i \delta(y_{12}) \quad (A2)$$

$$\frac{y_2}{y_{12}} + \frac{y_1}{y_{21}} - 1 = 2\pi i \frac{y_1 + y_2}{2} \delta(y_{12}). \quad (A3)$$

2. Sample calculations

Pictorial rules for setting up y -integrals are shown in Fig. 9 and some examples of applying these rules are given in Figs. 10–12.

In Fig. 10, the emergence of $y\delta(y)$ factor is shown when only three y_{2a} ’s in the y_{2a}^4 factor (produced via d -algebra) are cancelled by y_{2a}^3 factor present in the ghost propagator.

Actual evaluation of ‘ q ’ y -integrals (for the divergent pieces) is possible in ‘ $\leq q$ ’ steps as shown in the following sample calculations.

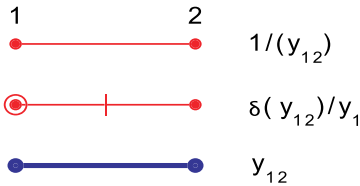


FIG. 9 (color online). Rules for setting up y -integrals.

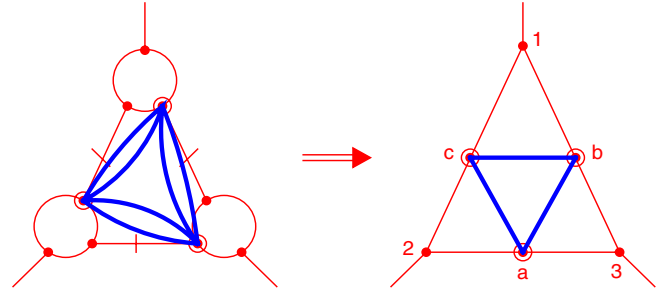


FIG. 11 (color online). Setting up y -integrals for diagram 1.(a) in Fig. 5.

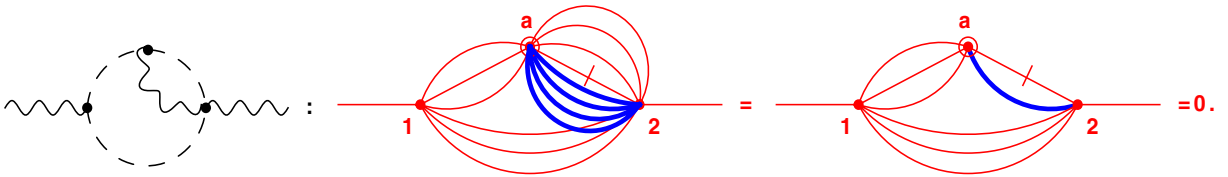
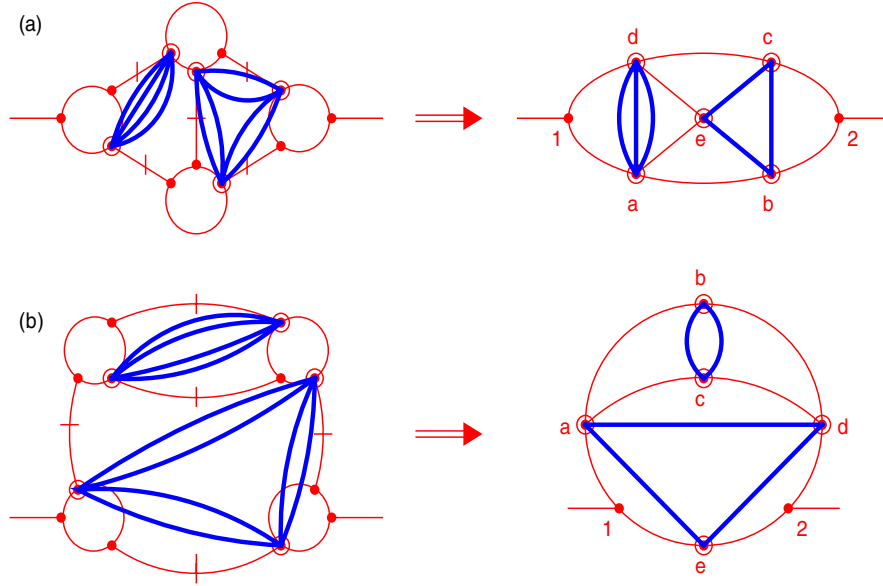


FIG. 10 (color online). Vanishing of a 2-hoops diagram with ghost propagators.

FIG. 12 (color online). Setting up y -integrals for the last two diagrams in Fig. 7.

$$\begin{aligned}
 \text{F.11} &\equiv \int \frac{dy_{1,2,3,a,b,c}}{y_a y_b y_c} \frac{V_1 V_2 V_3 y_{ba} y_{ac} y_{cb}}{y_{1c} y_{c2} y_{2a} y_{a3} y_{3b} y_{b1}} \\
 &= \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \oint dy_{a,b,c} \left(\frac{1}{y_{2a}} + \frac{1}{y_{a3}} \right) \left(\frac{1}{y_{3b}} + \frac{1}{y_{b1}} \right) \left(\frac{1}{y_{1c}} + \frac{1}{y_{c2}} \right) \left(1 - \frac{y_a}{y_b} \right) \left(1 - \frac{y_c}{y_a} \right) \left(1 - \frac{y_b}{y_c} \right) \\
 &= \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \oint dy_{a,b} \left(\frac{1}{y_{2a}} + \frac{1}{y_{a3}} \right) \left(\frac{1}{y_{3b}} + \frac{1}{y_{b1}} \right) \left(1 - \frac{y_a}{y_b} \right) \left(1 - \frac{y_2}{y_a} - \frac{y_b}{y_1} + \frac{y_b}{y_a} \right) \\
 &= \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \oint dy_a \left(\frac{1}{y_{2a}} + \frac{1}{y_{a3}} \right) \left(-\frac{y_a}{y_3} - \frac{y_2}{y_a} + \frac{y_2}{y_3} + \frac{y_a}{y_1} + \frac{y_1}{y_a} - 1 \right) \\
 &= \int dy_{1,2,3} \frac{V_1 V_2 V_3}{y_{12} y_{23} y_{31}} \left(-3 + \left[\frac{y_1}{y_2} \right] \right).
 \end{aligned}$$

$$\begin{aligned}
 \text{F.12.(a)} &\equiv \int \frac{dy_{1,2,a,b,c,d,e}}{y_a y_b y_c y_d y_e} \frac{V_1 V_2 y_{ad}^3 y_{bc} y_{ce} y_{eb}}{y_{1a} y_{ab} y_{b2} y_{2c} y_{cd} y_{de} y_{ea} y_{d1}} = \int \frac{dy_{1,2,a,b,d}}{y_a y_b y_d} \frac{V_1 V_2 y_{ad}^2 y_{bc}}{y_{1a} y_{ab} y_{b2} y_{2c} y_{cd} y_{d1}} \left(1 - \frac{y_a}{y_d} - \frac{y_b}{y_d} + \frac{y_b}{y_c} \right) \\
 &= \int \frac{dy_{1,2,a,b,d}}{y_a y_d} \frac{V_1 V_2 y_{ad}^2}{y_{1a} y_{ab} y_{b2} y_{d1} y_{2d}} \left(1 - \frac{y_a}{y_d} - \frac{y_b}{y_d} + \frac{y_b}{y_2} - \frac{y_d}{y_b} + \frac{y_a}{y_b} \right) = \int \frac{dy_{1,2,a,d}}{y_a y_d} \frac{V_1 V_2 y_{ad}^2}{y_{1a} y_{d1} y_{2d} y_{a2}} \left(3 - \frac{y_a}{y_d} - \frac{y_2}{y_d} - \frac{y_d}{y_a} \right) \\
 &= \int dy_{1,2,a} \frac{V_1 V_2}{y_{1a} y_{a2} y_{21}} \left(-6 + 4 \frac{y_a}{y_2} + 5 \frac{y_1}{y_a} - \left(\frac{y_a}{y_2} \right)^2 - \frac{y_2}{y_a} - \left(\frac{y_1}{y_a} \right)^2 \right) = \int dy_{1,2} \frac{V_1 V_2}{y_{12} y_{21}} \frac{1}{2} \left(2 - \left[\frac{y_1}{y_2} \right] \right) \\
 &\Rightarrow \frac{1}{2} \int d^8 \theta \int dy_1 dy_2 \frac{V_1 V_2}{y_1 y_2} = 0.
 \end{aligned}$$

$$\begin{aligned}
 \text{F.12.(b)} &\equiv \int \frac{dy_{1,2,a,b,c,d,e}}{y_a y_b y_c y_d y_e} \frac{V_1 V_2 y_{bc}^2 y_{ae} y_{ed} y_{da}}{y_{1a} y_{ba} y_{ac} y_{cd} y_{db} y_{d2} y_{2e} y_{e1}} = - \int \frac{dy_{1,2,a,b,d,e}}{y_a y_d y_e} \frac{V_1 V_2 y_{ae} y_{ed}}{y_{1a} y_{ba} y_{db} y_{d2} y_{2e} y_{e1}} \times \left(-2 + \frac{y_b}{y_a} - \frac{y_d}{y_b} \right) \\
 &= - \int \frac{dy_{1,2,a,d,e}}{y_a y_d y_e} \frac{V_1 V_2 y_{ae} y_{ed}}{y_{1a} y_{d2} y_{2e} y_{e1}} (-2 + 1 + 1) = 0.
 \end{aligned}$$

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